Set 21 : Voltage-to-frequency converters

You may not find many voltage-to-frequency converter circuits classified as such. They are likely as not to be found under such headings as voltage-controlled oscillators, frequency modulators, astable circuits, and even waveform generators, as the following article—an elementary introduction to their operation—points out. Decisions on which kind to use may often centre on linearity. The closed loop designs generally have better linearity, typically 0.1 to 0.5%, than the simpler open-loop designs, especially the "charge dispensing" kind, discussed in the article (see, for example, page 19). The unijunction type, page 10, also crops up on pages 116 & 130, and a further $\Delta\Sigma$ circuit on page 117.

Voltage-to-frequency converters

Voltage-controlled oscillators—astable multivibrators—waveform generators—frequency modulators: under each of these headings one finds circuits that have an important common property, that the output frequency is a function of some reference or control signal. Such circuits are multi-variable systems in which several parameters of the output waveform are controlled singly or in various combinations by other parameters at the input. Thus the same circuit can appear under different headings depending on which input/output relationship is of priority concern.

As an example, some recent integrated circuits have been designed as waveform generators with square/triangle/sine wave outputs. If the output waveform is of no particular concern, the fact that the frequency of each output is proportional to a direct control voltage assumes a greater importance. The circuit can then be called a voltage-controlled oscillator. Now assume that the control voltage is set to a particular quiescent value with a smaller alternating voltage superimposed. Then the output frequency is modulated by the a.c. input, with the carrier frequency corresponding to the quiescent value of control voltage. The label for this circuit is frequency modulator.

In set 21 of Circards the primary property of interest is the relationship between an input voltage or current and the frequency of the output, with much less importance being attached to the wave shape or amplitude. A particularly desirable property is that the voltage-to-frequency relationship be linear, and in extreme cases departures from linearity of as little as 0.01% may be desired. In the process of achieving this, the output pulse height and width may have to be equally well controlled but these are a means to the end and not an end in themselves. There are other cases where the frequency needs to be varied only over a limited range, demanding only a small linear region to the V/f characteristic. A good example is found in the design of v.c.os for high-frequency phase-locked loops. Restriction of the frequency range and of linearity is a compromise accepted more or less willingly in exchange for a speed capability that matches that of the associated digital circuits.

In nearly all of these examples, the basic timing mechanism is that of charging a capacitor from a control voltage or current. The voltage change across the capacitor is sensed by some level-detecting circuit which activates an electronic switch
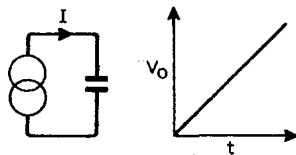

Fig. 1. Constant charging current allows repetition frequency to be made proportional to current.
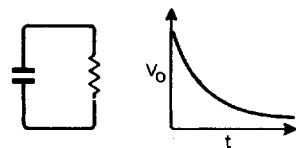

Fig. 2. To cause charging cycle to recommence, a low-value resistor is switched across the capacitor to discharge it quickly.
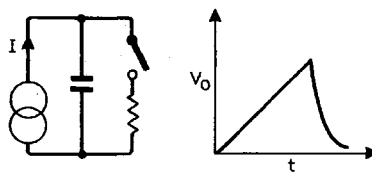

Fig. 3. If discharge time is made small enough the charging current can remain connected. Level of capacitor voltage is used to operate discharge switch.
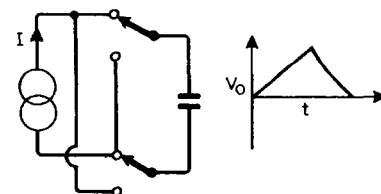

Fig. 4. Triangular waves with repetition frequency proportional to current are produced by reversing capacitor charging current.

to discharge the capacitor and restart the cycle. Two categories of circuit can be clearly distinguished:
● where the discharge time of the capacitor is made short compared with the shortest charging time and need not be under the control of the input voltage, and
● where both charge and discharge times are controlled in common by the input. The first-mentioned circuits produce sawtooth waveforms across the capacitor and short duration output pulses, while the last-mentioned commonly develops a triangular wave across the capacitor, in association with a square wave at a separate output.

These ideas are illustrated in Figs 1 to 4. In Fig. 1, constant current results in a constant rate-of-change of voltage across the capacitor, i.e. the time taken to charge to a given p.d, will be inverse to the charging current. If that level can be sensed and caused to end the cycle or half-cycle, then the repetition frequency (being inverse to the period of the waveform) will be proportional to the current and a linear I/f converter results. The simplest way of causing the cycle to recommence is to place a low-value resistor across the capacitor to discharge it in the shortest possible time. If the discharge current is large compared to the charging current, then it is immaterial whether the charging current is disabled or not and Fig. 3 represents the basic principle of many V/f converters, with the switch periodically closing at the instant when the p.d. across the capacitor reaches a defined value.

An alternative principle is shown in Fig. 4. The current generator is applied to the capacitor in the reverse direction giving an opposing slope to the ramp but of equal magnitude. The resulting waveform is triangular with the repetition frequency linearly related to the current if the points at which switching is initiated are defined. The provision of a purely electronic two-pole change-over switch is difficult, and the reversal of current direction is more often achieved by using a single-pole switch or its equivalent to control the current generator directly.

A second problem that often arises is that the changing p.d. across the capacitor affects the nominally constant current. This is obvious in terms of the non-linearity of the ramp, but may not affect the linearity of the
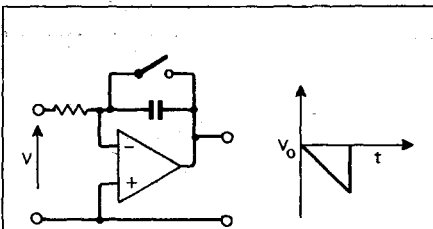
Fig. 5. Using the charging capacitor in an op-amp integrator ensures current is independent of capacitor p.d.
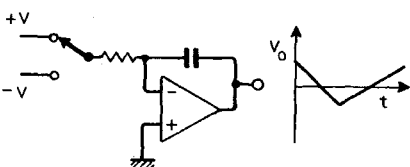

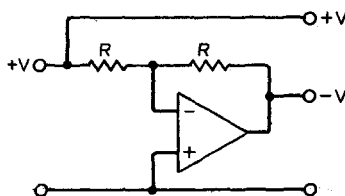*Fig. 6. Simple form of triangular-wave generator uses principle of Fig. 5.*

Fig. 7. Circuit provides equal +V and −V inputs for Fig. 6 with an op-amp of −1 gain.

V/f function provided the waveshape is well controlled, e.g. accurate V/f conversion is possible with simple R-C charge and discharge circuits though the wave shape is highly non-linear. Where waveshape is also of importance, the capacitor forms part of an operational amplifier integrator circuit, with the virtual earth action ensuring that the charging current is independent of the p.d. The discharge element now has no point connected to ground which can raise problems in activating it. (Fig. 5.)

This technique leads to a simple form of triangular-wave generator shown in Fig. 6 where both the $+V$ and $−V$ inputs have to vary together if the slopes are to remain of equal magnitude. By using both the input and the output of an amplifier with a voltage gain of $−1$ this is readily achieved (Fig. 7). Alternative methods include the design of amplifiers whose voltage gain is switched from $+1$ to $−1$, and of integrators in which the direction of capacitor current is reversed by a switch while the magnitude is controlled by a single input voltage.

In all of these circuits there remains the problem of the level sensing circuitry that is to determine the instant of switching; both switching speed and accuracy of level are important making the design of a fast, accurate V/f converter a difficult one.

The term charge-dispensing is a big one in the literature on precision V/f converters. A feedback system is set up in which the output pulses from a generator (basically

monostable in form) are arranged to feed back a constant amount of charge for each output pulse. If these units of charge are combined at the input of the system with the control signal, and the overall feedback is negative, then the pulse rate will be proportional to the control signal.

In block-diagram form in Fig. 8, the principle is illustrated by a combination of V/f and an f/V converter. Assuming that the amplifier gain is high, and that the f/V convertor is very linear then the feedback overcomes any non-linearities in the V/f converter, i.e. $V_o = V$ to a high accuracy because of the feedback while $V_o \propto f$ ensuring that $f \propto V$ without reference to the linearity of the V/f converter. The f/V converter might be of the diode-pump variety which with suitable design can transfer a fixed charge into a load for each output pulse rate.

A level-sensing monostable gives an output pulse when the input level rises above a critical value. If the input then falls a second pulse is generated on the next excursion through the set level in the same sense. An important restriction is that the capacitor shall have been completely discharged prior to the second pulse—otherwise the time taken for recharging will be shortened and the output pulse-width reduced. The output of such a monostable would ideally be a train of constant-amplitude constant-width pulses, which could be smoothed and fed back to the input amplifier as in Fig. 9.
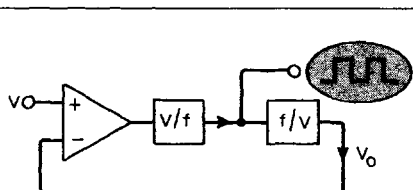

Fig. 8. In this "charge-dispersing" system, a constant amount of charge for each output pulse is fed back so that pulse rate can be proportional to the control signal.
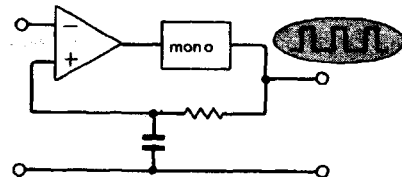

Fig. 9. Monostable circuit produces output pulse when input exceeds a certain level, in either sense.
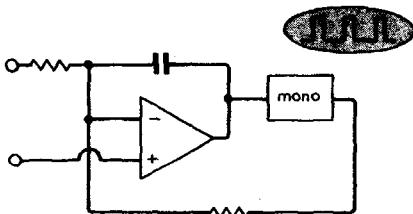

Fig. 10. An alternative arrangement is to dispense charge into a summing integrator. Output pulse rate is a linear function of control voltage or current.
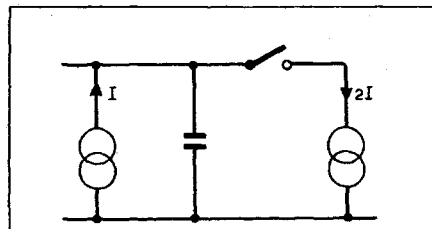

Fig. 11. Technique of using two current sources, but switching only the one having twice the value of the other, is used in some i.cs.
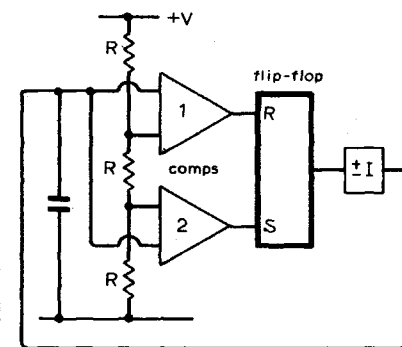

Fig. 12. Triangular wave generator using technique of Fig. 11. Comparator reference inputs are set to 2V/3 and V/3, the capacitor voltage ranging between these limits.

A better arrangement dispenses these units of charge into a summing integrator—Fig. 10. For positive pulses a negative control voltage is required, the integrator output ramping up until a pulse is produced from the monostable. The charge dispensed into the summing junction causes the output of the integrator to fall, again rising slowly under the action of the control current. On average, the net charge inflow has to be zero, the charge dispensed per pulse is constant and hence the pulse-rate is a linear function of the control voltage/current.

Other recent i.cs revert to the separate constant current circuit for timing circuits and waveform generators, and the resulting I/f linearity can be accurate enough for many applications. One technique is to have two current sources one set by the external control voltage, the other of opposite polarity but of twice the magnitude—Fig. 11. Keeping the former permanently on and switching the latter on and off makes the net current in the capacitor change from $+I$ to $−I$. A circuit configuration to use this technique to produce a triangular-wave generator is shown in Fig. 12.

Two comparators sense the capacitor voltage, their reference inputs being set to $+V/3$ and $+2V/3$ by an internal potential divider. Assume the current at I; the capacitor charges until its p.d. reaches $+2V/3$. Comparator 1 changes its output and resets the flip-flop. This reverses the direction of current flow until the capacitor discharges to $+V/3$. The comparator 2 operates setting the flip-flop into its original state and restarting the cycle.

Unijunction voltage-to-frequency converter
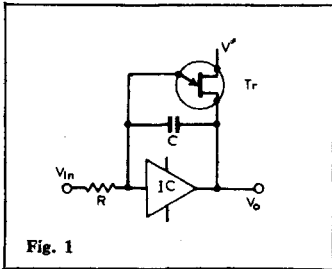
Fig. 1

Components
IC 741, ±15V supplies
Tr 2N2646
C 10nF
R 100kΩ
V' 3.3V
V_{in} see graph
V_o see graph

Fig. 2

Fig. 3
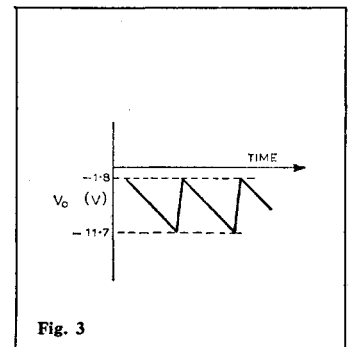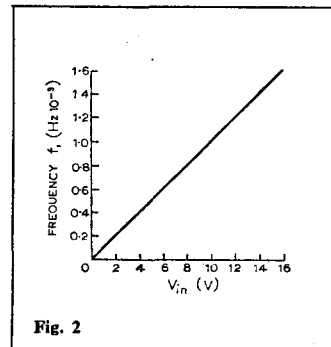
Circuit description
With the removal of the unijunction transistor the circuit of Fig. 1 is simply an integrator which, with a positive V_{in}, gives a negative-going ramp V_o. If the i.c. gain is sufficiently high then V_o is $-V_{in}t/RC$. The unijunction serves to discharge the capacitor each time the voltage between e and b_1 reaches the unijunction trigger voltage. The circuit therefore goes through the cycle shown right. Upper limit of -1.8V is the voltage at which the unijunction reverts to being an open circuit. Lower limit of -11.7V is arbitrary and is the result of choosing V', R and C so that $V_{in}=10$V gave a frequency of 1kHz. With ±15V supplies this obviously cannot be extended beyond 15V.
The degree of linearity in the plot of frequency against V_{in} shown in Fig. 2 is quite high e.g. 10V gave 1kHz, 5V gave 498Hz, 1V gave 96Hz and 0.15V gave 16Hz.
Rise time of the output waveform (Fig. 1 circuit gave the waveform of Fig. 3) corresponding to the time when C is discharging, was 15μs i.e. 1.5% of the period at 1kHz, so the circuit cannot be recommended for much higher frequencies.
But from the expression for the downward ramp it is clear that the same frequency range can be achieved by the use of different values of R and C, and also of V'. It will, of course, be generally desirable to keep R relatively high to give high input impedance.
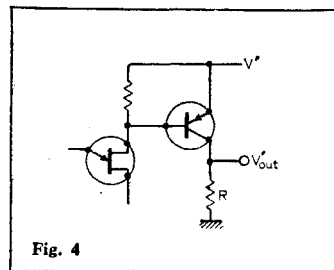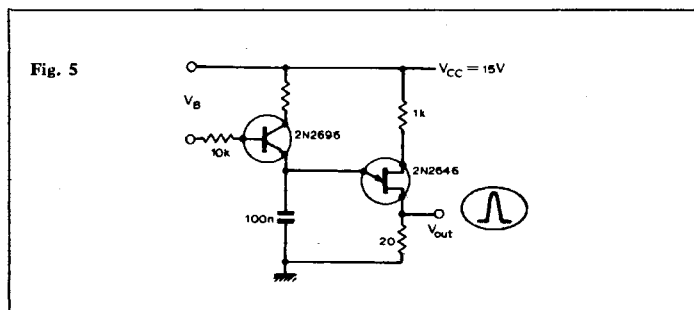

Fig. 4

Circuit modifications
The modification shown in Fig. 4 to the circuitry around the unijunction transistor will provide a pulse train at V'_o, the frequency being the same as that of the main circuit. The leading edge of this pulse train will correspond to the rising edge of V_o shown in Fig. 3. This V'_o will, of course, have the advantage of going much closer to zero in the time between the pulses.
An alternative voltage-to-frequency converter reported by Swarup and Banerjee is shown in Fig. 5. It is basically a unijunction oscillator with constant-current drive to the capacitor, this

current being proportional to the voltage V_B.
A linear relationship between V_B and the output frequency is claimed in the range 0 to 500Hz. The basic action of the unijunction oscillator and modifications to reduce the discharge time of C are fully described in Circards set 3 (waveform generators) card 4.

Reference
Swarup & Banerjee, Linear voltage to frequency and voltage to pulse width converters using unijunction transistors. *Int. J. Electronics*, vol. 32, 1972, pp. 377-81.

Fig. 5

Multiplier voltage-to-frequency converter

Fig. 1

Typical performance
Supplies $\pm15V$, $\pm8.5mA$
IC_1 XR2308 IC_2, IC_3 741
D_1, D_2 3.3V Zeners R_1, R_3 22kΩ
R_2, R_6 330kΩ R_4, R_5 68kΩ
R_7 100kΩ R_8, R_9, R_{10} 10kΩ
R_{11} 2.2kΩ C_1 22pF, C_2 1nF
See Fig. 3 for graph of f/V_c and
Fig. 2 for waveforms.

Fig. 2

Fig. 3

Fig. 4

Fig. 5
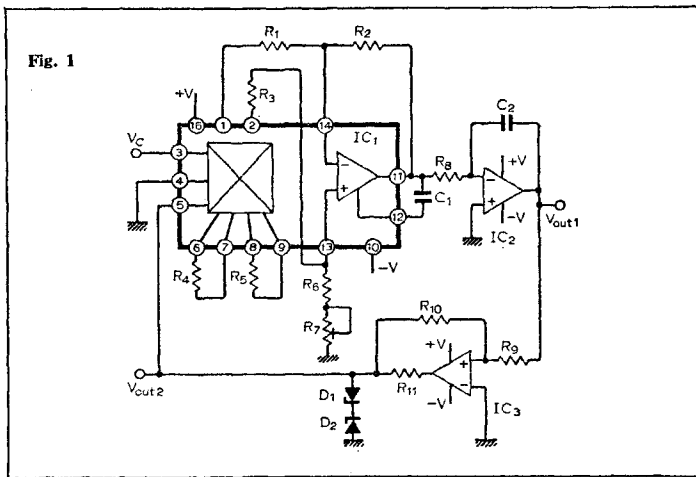
Circuit description
The circuit of Fig. 1 is basically a closed-loop integrator-comparator square-triangle generator, comprising IC_2 and IC_3, with a multiplier (IC_1) inserted in the loop to provide control of frequency. The value of the output voltage from the multiplier is a scaled version of the product V_{out2} and the control voltage V_C. Thus the amplitude of the signal to be integrated is directly proportional to a scaled value of the control voltage. A positive voltage applied to the inverting integrator charges C_2 with its output end negative relative to the input end (held close to 0V by negative feedback through C_2 and the high gain of IC_2). Thus, V_{out1} goes negative until the current it feeds through R_9 exceeds the positive current in R_{10}, resulting in a negative current to the non-inverting input of the Schmitt comparator. V_{out2} then rapidly switches to a negative value due to positive feedback applied to IC_3, causing the multiplier output to go negative (V_c is always positive). The output from the integrator then starts rising until it reaches a positive voltage sufficient to make the comparator change its state again, returning V_{out2} and the multiplier output to their original positive values. Hence, V_{out1} is a triangular wave and V_{out2} a square wave with frequency linearly dependent on the control voltage

Component changes
Useful range of supplies: ±7 to $\pm16V$.
Increase C_2 to reduce upper frequency limit.
Useful range of V_c is about 0 to $+11V$.
Changing IC_3 to a 301 type op-amp increases slew-rate capability.
R_9 can have a wide range of values the lower limit being imposed by heavy loading of IC_2 and the upper limit by the failure of IC_3 to switch before it saturates.

Circuit modifications
● Accuracy of frequency control largely depends on the nonlinearity and offset voltages in the multiplier part of the loop. Output offset adjustment is provided by R_7 and independent adjustment of the offset voltages at the multiplier's X and Y inputs (pins 3 and 5) can be obtained by the 25-kΩ potentiometers R_{12}, R_{13} shown in Fig. 4, where R_{14}, R_{15} are 100kΩ.
● For a given value of control voltage frequency depends on the scale factor of the multiplier. Adjusting this allows the output frequency to be made a simple linear function
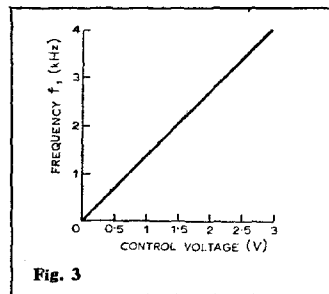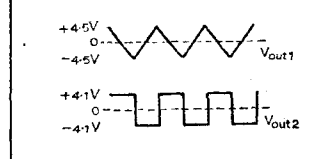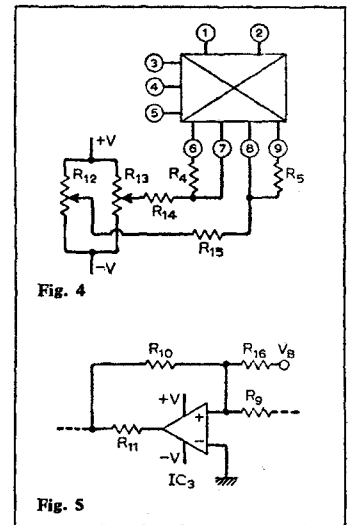
of V_c. The factor can be adjusted in three ways: (1) by adjusting the op-amp gain in the multiplier block by means of R_2, (2) by adjusting the gain of the multiplier block by varying R_4 and R_5, and (3) by connecting the V_{out2} signal to the Y input of the multiplier (pin 5) through a ground-referred potentiometer.
● Asymmetry in the output waveforms due to mismatched Zener diodes can be corrected by applying a bias voltage V_B of suitable polarity to the comparator input via R_{16}, as shown in Fig. 5. Alternatively, this arrangement with $V_B=\pm V$ and $R_{16}=10k\Omega$ can be used to purposely introduce a d.c. offset into the output waveforms.
● Other methods may be used to limit the amplitude of the output voltage from the comparator, e.g. by using a diode bridge limiter or by replacing IC_3 with an op-amp of the type providing access to the drive point of its output stage, such as a 748. This allows the comparator output to be

clamped by zener diodes or suitably-biased transistors connected to the output stage drive point.
● For higher frequency operation the multiplier/op-amp block can be replaced by a separate multiplier (MC1495) and inverting amplifier (LM318), the 741-type integrator replaced by an LM318 integrator and the Schmitt replaced by an LM311.
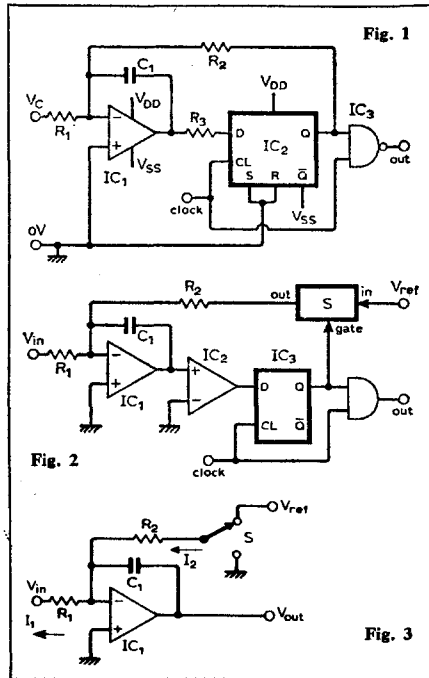
Further reading
Graeme, J. G. Applications of operational amplifiers, McGraw-Hill 1973, pp. 161/2.
Graeme, J. G., Tobey, G. E. & Heulsman, L. P. Operational amplifiers, McGraw-Hill 1971, pp. 237-51.
XR-2208/2308 operational multiplier data sheet, EXAR Integrated Systems Inc. 1972.
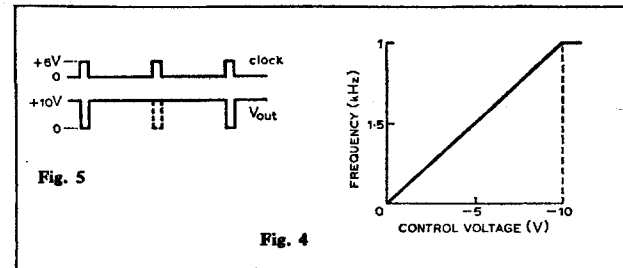
Delta-sigma voltage-to-frequency converter

Fig. 1

Fig. 2

Fig. 3

Typical performance of Fig. 1
IC_1 741, IC_2
$\frac{1}{2} \times$ CD4013AE
IC_3 $\frac{1}{4} \times$ CD4011AE
Supplies V_{DD} +10V
V_{SS} −10V
R_1, R_2 100kΩ
R_3 1kΩ
C_1 100nF
Clock 6V positive pulses,
p.r.f. 1kHz, duty cycle 10%
See Figs 4 and 5.

Fig. 5

Fig. 4

Circuit description

A class of voltage-to-frequency converter gives an output in the form of a pulse train where the repetition frequency is directly proportional to the instantaneous value of the control voltage but the pulses are generated asynchronously. The output from a delta-sigma encoder is again a pulse train but its average pulse repetition frequency is proportional to the control voltage and the pulses are generated in synchronism with a clock pulse waveform.

The basic form of a delta-sigma modulator is essentially a voltage-to-pulse ratio converter (Fig. 3). The circuit maintains a constant voltage across C_1 as the input voltage is varied, which requires that the charging current from the voltage reference source to be switched into C_1 at a repetition rate that attempts to keep the net change in voltage across C_1 at zero. Thus the rate at which the reference current must be switched into the capacitor must be proportional to the input voltage. If the reference current is switched under the control of a stable clock-pulse

generator the output pulses will be proportional to V_{in} and synchronized with the clock pulse source. Assuming that the net voltage across C_1 is zero, that V_{in} is negative, that V_{ref} is positive and IC_1 is a high-gain op-amp then $I_1=I_2$, V_{out} (mean) $=0$ and I_{out} (mean)$=0$. As the inverting input of IC_1 is a virtual earth, $I_1=V_{in}/R_1$ and $I_2=kV_{ref}/R_2$ where k is pulse duty cycle required to keep $I_2=I_1$. Equating these currents gives

$$\frac{V_{in}}{R_1}=k\frac{V_{ref}}{R_2},$$

where k is the ratio of the output pulse repetition rate (f) to the clock pulse repetition rate (f_c). Hence

$$f= \left(\frac{R_2 f_c}{R_1 V_{ref}}\right) V_{in}.$$

By making $R_2=R_1$ and $V_{in(max)}=V_{ref}$ the maximum output p.r.f. is that of the clock source and the average output pulse rate is proportionally smaller for smaller values of V_{in}.
The arrangement of Fig. 2 uses an analogue transmission gate to realize the switch S.

IC_2 is a precision comparator which determines when the reference voltage source is to be switched to R_2 by monitoring the polarity of the output from the integrator IC_1. This switching action is synchronized to the clock pulses by using gating pulses derived from the output of a D-type flip-flop which receives the comparator's output at its data input.
The circuit of Fig. 1 is that to which the typical performance data refers. This is a simplified form of the arrangement previously discussed with the electronic switch, separate reference source and precision comparator removed. (Note that whilst the integrator used both positive and negative
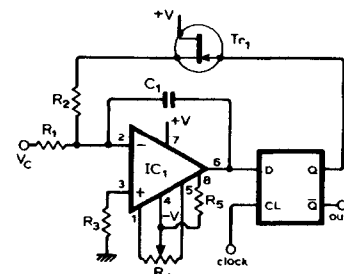
supplies the D-type flip-flop is connected only across the positive supply.) As the D-type produces output pulses equal in amplitude to the V_{DD} rail voltage only when its data input receives a positive pulse from the integrator, a separate switched reference is not essential. Also, the precision comparator can be replaced by R_3 which limits the negative-going pulses to the data input of the D-type which acts as the comparator. Average frequency/V_c graph (Fig. 4) has a linearity of $\pm 0.1\%$ up to $f=f_c$ when $V_c=V_{DD}$. No further increase in frequency is possible except by increasing the p.r.f. of the clock source. Output pulse waveform of Fig. 5, inverted by IC_3, is of $V_c=V_{DD}/2$, the dashed pulse only being present when V_c is raised to V_{DD}.
The circuit of Fig. 6 is another simplified form of the more general system where the comparator had been omitted and the electronic switch is realized by a junction f.e.t. The positive supply rail is used as the voltage reference source and the output is taken from the $\bar{Q}$ terminal of the D-type flip-flop IC_2, which is a complementary m.o.s. version to conserve power. This circuit is capable of linear v-to-f conversion within $\pm 0.05\%$ almost independently of temperature changes. Typical values are:
V ± 2.7V
IC_1 LM4250C
IC_2 $\frac{1}{2} \times$ MC14013CL
R_1, R_2, R_3, R_4 100kΩ
R_5 5.6MΩ, C_1 100nF
Tr_1 2N4396

Fig. 6

Further reading
Defreitas, R.Low-cost way to send digital data, *Electronics Design*, pp. 68-73, Jan. 18. 1974
Ross, P. J. Simple accurate voltage to frequency converter. *Jnl. of Physics E*, vol. 7, pp. 706/7.
Alusten, B. Calculate with a v-f converter, *Electronics Design*, June 7, 1974, pp. 130-2.

Sinewave voltage-to-frequency converters
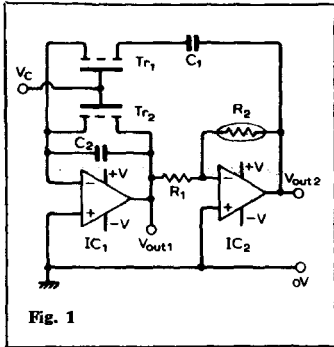
Fig. 1

Typical performance
Supplies ±15V
IC$_1$, IC$_2$ 741
Tr$_1$, Tr$_2$ 1/6 × CD4007AE
R$_1$ 150Ω
R$_2$ thermistor type R13
C$_1$, C$_2$ 100nF
V$_{out1}$ 520mV pk-pk
V$_{out2}$ 1.04V pk-pk
See graph for f/V$_c$ (Fig. 2)

Circuit description
This circuit (Fig. 1) is one of
the many forms of Wien bridge
oscillators with Tr$_1$ and C$_1$
forming the series-connected
frequency-dependent arm with
Tr$_2$ and C$_2$ forming the parallel
connected arm of the bridge.
For oscillation to occur the
closed-loop gain must be unity,
the required amount of gain
being provided by the inverting
operational amplifier IC$_2$, the
gain being determined by the
ratio R_2/R_1. With this
configuration the common-
points of the frequency-
determining resistors are
connected to the virtual-earth
inverting input of IC$_1$. This is
a convenient arrangement for
replacing these resistors with
elements which have a resistance
that can be controlled by a
ground-referred voltage source.
In the above circuit these
elements take the form of a
pair of matched c.m.o.s.
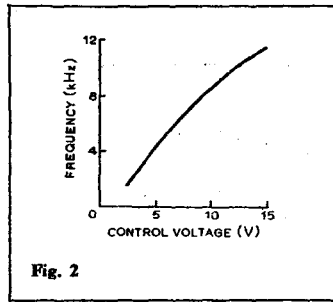transistors which have gate-
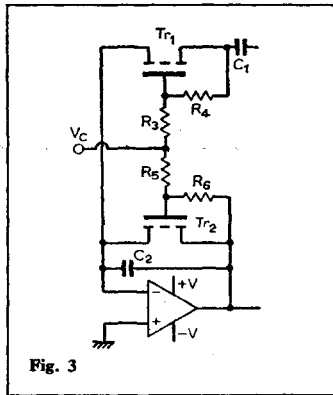source resistances that depend

Fig. 2

Fig. 3

on the control voltage V$_c$.
Linearity of the voltage-to-
frequency conversion
characteristic is not particularly
good over a wide range of
frequencies but may be
adequate for many purposes
where only a restricted
frequency range is required.
Resistance of the f.e.ts
depends on their drain-source
signal voltages as well as on the
control voltage V$_c$ but this can
be reduced, and the linearity
of f.e.t. resistance-to-control
voltage characteristic linearized,
by using local feedback around
the f.e.ts as shown in Fig. 3,
where R$_3$, R$_4$, R$_5$ and R$_6$ may
be of the order of 1MΩ.
If the closed-loop gain deviates
from unity the amplitude of
oscillation will vary with time,
so to avoid extremely precise
setting of gain it is initially set
slightly high and then
automatically controlled
the a.g.c. being achieved with
a thermistor in the above circuit.
In addition to the use of local
feedback on the f.e.ts, these
elements could be connected
to form only part of the
frequency-determining
resistances with bulk of the
values in the form of series-
connected resistors which
would tend to swamp out the
non-linearities in the f.e.t.
whilst restricting the range of
control.
The f.e.ts could be replaced by
matched photoconductive
resistors or by bipolar
transistors which are switched
on and off by current pulses to
the bases, the mean collector-
emitter resistance being
controlled by the pulse

repetition frequency.
A voltage-to-frequency
converter using a pair of
all-pass active networks is
shown in Fig. 4. These
networks, using A$_1$ and A$_2$,
have a constant gain magnitude
but a phase shift given by
$\phi_1 = -2\tan^{-1}(\omega CR_1) - 180°$ and
$\phi_2 = -2\tan^{-1}(\omega CR_2) - 180°$
respectively. With the 180°
phase shift through the a.g.c.
amplifier A$_3$ the circuit will
oscillate at a frequency
$1/(2\pi C\sqrt{R_1R_2})$Hz, which shows
that a voltage-to-frequency
conversion may be obtained by
making R$_1$ or R$_2$ or both
voltage-dependent resistors,
e.g. f.e.ts. For a wide range of
frequency variations R$_1$ could
be a voltage-dependent resistor
and R$_2$ a range-switching
resistor. For $R = R_1 = R_2$ the
outputs are generated with a
controllable phase difference
$\phi = (\phi_1 - \phi_2) = -2\tan^1(\omega CR)$.
Circuit of Fig. 5 uses two active
integrators and two multipliers
to produce a voltage-to-
frequency converter having
quadrature outputs that can
have a very fast response to
changes in V$_c$ provided a fast
a.g.c. system is added to the
basic circuit. Under this
condition the circuit will
oscillate at a frequency which
allows the double integration
to take place without changing
the amplitude of the signal.
Multiplier M$_2$ provides an
output $V_2 = +V_c \cdot V_{out1}/10$ and
M$_1$ gives an inverted output,
to maintain the loop phase
shift, of $V_1 = -V_c \cdot V_{out2}/10$.
With the 1/10 scaling factor,
frequency of oscillation is
$V_c/20\pi RC$. Multiplier M$_1$
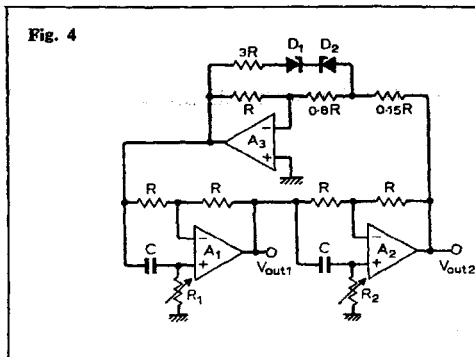could be replaced by an
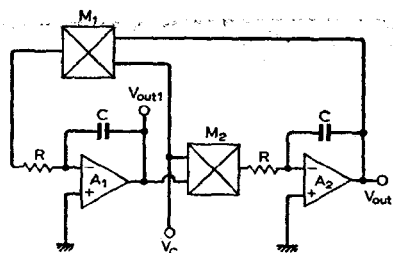inverting operational amplifier.

Further reading
Von Ow, H. P., Reducing
distortion in controlled
attenuators using FETS.
Proc. IEEE, 1968, pp. 1718/9.

Fig. 4

Fig. 5

Multiphase voltage-to-frequency converter

Fig. 1

Typical data
IC$_1$ to IC$_6$ 74IC
Tr$_1$, Tr$_2$ 2N5457
R$_1$, R$_{11}$ 20kΩ
R$_2$, R$_3$, R$_{12}$, R$_{13}$, R$_6$, R$_7$, R$_{10}$, R$_{14}$ 10kΩ
R$_4$, R$_5$, R$_8$, R$_9$ 2.7kΩ
C$_1$, C$_2$ 47nF
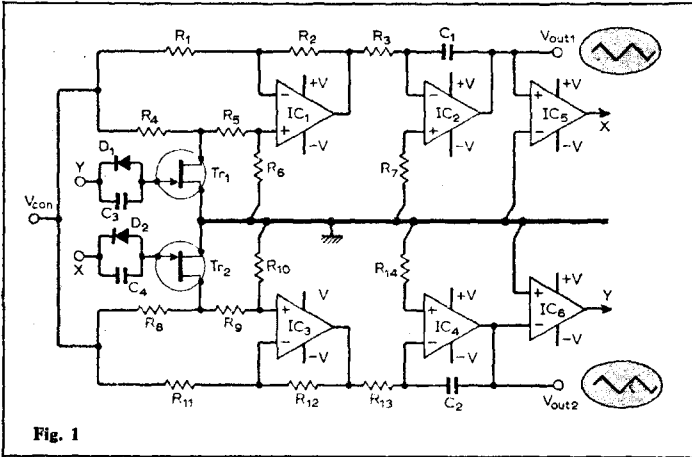C$_3$, C$_4$ 68pF
D$_1$, D$_2$ 1N914

Fig. 2

Fig. 3

Fig. 4

Circuit description
This is a twin circuit based on R-C integration to provide the triangular waveform and level sensing to provide a square wave which operates an electronic switch controlling polarity applied to the integrator. Outputs X and Y are cross-connected giving control of electronic switches Tr$_2$ and Tr$_1$ respectively and triangular waveforms which are 90° out of phase. IC$_5$ and IC$_6$ provide high open-loop gain, and at low frequencies provide faster switching than comparators. V$_{out1}$ is a positive-going ramp until Tr$_1$ changes state and this occurs at the instant of zero-crossing of V$_{out2}$, which then switches IC$_6$. V$_{out1}$ then ramps down and changes the state of Tr$_2$ when a zero-crossing point is reached. The time taken to go from say a positive peak to zero level depends on the RC time constant and the value of V$_{control}$. It should be noted that as no amplitude controls for the output are imposed, one or other of the integrators

will reach saturation before the other output reaches its zero crossing point.

Circuit modifications
● Use a switched integrator rather than a switched gain amplifier. This makes IC$_1$, IC$_3$ redundant (Circard Set 3, No. 5). LM3900 quad package may be now arranged to provide the two outputs.
● Phase shift oscillator (above) provides three outputs with 60° phase relationship.
IC$_1$–IC$_3$: 1/6 × CD4049,
R: 10kΩ, C: 2700pF,
frequency: 13kHz.
As the c.m.o.s. gates are being used in their linear region, both the n- and p-type transistors will be conducting and hence power consumption will depend on the supply voltage. Typically the total current drain from the supply for the above network is
V$_{DD}$ − V$_{SS}$ = 3V   I$_T$ = 0
V$_{DD}$ − V$_{SS}$ = 10V   I$_T$ = 12mA
V$_{DD}$ − V$_{SS}$ = 15V   I$_T$ = 30mA
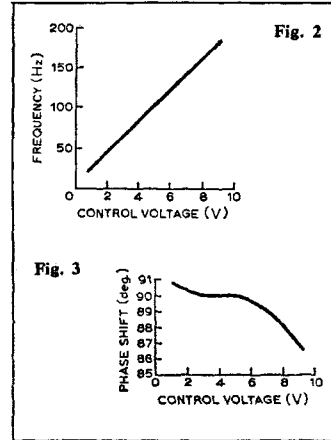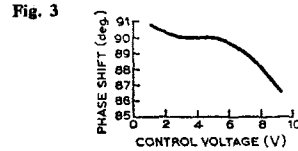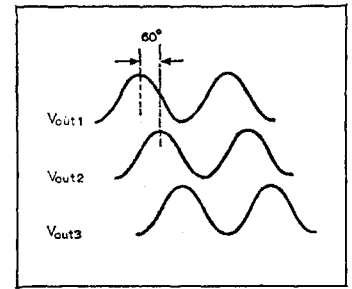Frequency may be controlled by substituting voltage-dependent resistors for each R$_1$
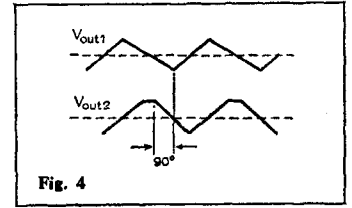
and maintaining as close a ratio as possible between the R values. Frequency is approximately 1/3RC.
Note that with the CR values necessary for 60° phase shift at a specific frequency, the output of each buffer stage is attenuated by about one half and hence the minimum gain of each stage must be > 2.
● An alternative arrangement is shown above right, using similar c.m.o.s. buffer inverters. In this case the resistor ratio is critical and theoretically for infinite gain amplifiers R$_2$ = R$_1$/2 and a much better approximation to sinusoidal outputs is obtainable from each buffer, again phase shifted by 60°. Typical values R$_1$:100kΩ, R$_2$: 33 to 39kΩ, C: 2700pF, V$_{DD}$ − V$_{SS}$ = 6V, frequency 1kHz.

These buffers have gain-frequency responses which give higher gains for lower supply voltages. Typically 50dB at +3V up to 100Hz, and 30dB at +10V up to 100kHz. Hence since the gains are finite, then R$_2$ must be less than R$_1$/2. But at the lower values of the supply range 3 to 15V, some flexibility of this value between each R$_2$ is permitted. At higher levels the ratio is more critical, R$_2$ may be replaced by f.e.ts employed as v.c.r. to obtain a restricted frequency range.
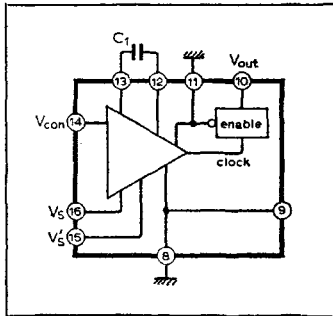
Further reading
Voltage controlled two-phase sawtooth oscillator, *Wireless World*, June 1973, p. 285.
AN-88 CMOS Linear Applications, National Semiconductor, p. 170.
Frequency controllable 3-phase sinewave generator, *Electronic Engineering*, July, 1974.
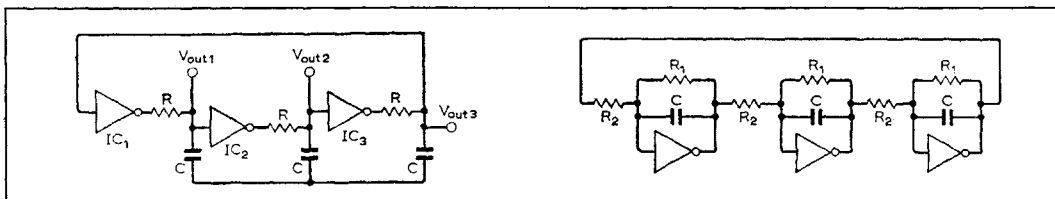
Cross references
Set 11, card 6.
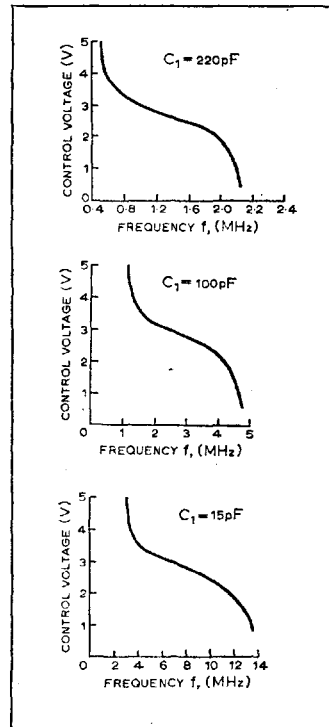Set 8, card 1.

Monolithic voltage-to-frequency converters

Typical data
IC $\frac{1}{2}$SN74S124N
C_1 220pF
$V_s = V'_s$ +5V d.c.
Frequency range 0.7 to 1.8MHz
(approx. linear)

Circuit description
An emitter-coupled astable multivibrator uses a single capacitor for timing. The circuit has high switching speed because charge storage effects are avoided by using the transistors in a non-saturated mode. This circuit is the basis of the above medium-scale integration package, where variable frequencies are obtained by charging the external capacitor at different rates via an internal voltage-controlled current source. The i.c. package contains two identical networks, but if only one is being used, it is essential that both ground connections (pins 8 & 9) are earthed to ensure earthing of the substrate and good isolation. The enable terminal (no. 11) must be grounded for continuous output at the output terminal. Output is disabled if this terminal is taken to logic high or open-circuited. Graphs opposite indicate linearity over a restricted range for each capacitor value, and waveform deteriorates at very low values of C_1, and thus at high frequencies.

Circuit modification
● Emitter-coupled astable output swings are usually restricted. An additional output stage supplied via V'_s permits the output swing to be approximately 0V up to V'_s and hence t.t.l. compatibility is easily achieved, i.e. V'_s and V_s need not be the same.
● Variable-capacitance diodes may provide a wider frequency range, depending on type (see over). Supply voltage 4.5 to 6.5V, frequency maintained constant.
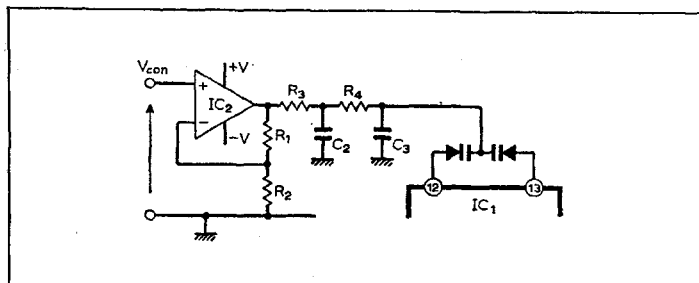
Components (circuit above)
Supply ±10V
IC_1 SH74S124N IC_2 LM301
R_1 R_2 10kΩ
R_3 R_4 100kΩ
C_2 C_3 1μF
C_4 C_5 MV16408

IC_2 is connected as a non-inverting amplifier with a voltage gain of two, so that the biasing voltage in this case is twice the control voltage. This gain can be altered for appropriate voltage range. A claimed frequency range of 2 to 20MHz using varactors MV1403 and MC1456 for IC_2 is documented in the referenced literature.
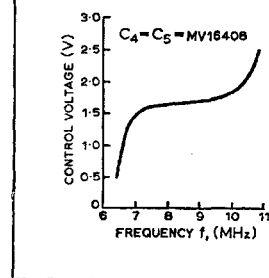
Components (circuit right)
IC_3 LM566, SE/NE566
General-purpose voltage-controlled oscillator.
C_T 4.7nF C_6 0.047μF
R_s 4.7kΩ R_T 10kΩ
Maximum sweep rate 1MHz
R_T and C_T are the frequency range determining components. For a fixed value of C_T 10:1 variation in frequency is possible via a variable input at $V_{control}$ which should be within the range 3 to 5.5V for $V_{cc} = \pm6V$.

The above values provide for a maximum free-running frequency of about 10kHz for Tr_1 off. For $V_s = -3V$, Tr_1 is saturated, hence increasing timing capacitor 10 times, free-running frequency is then approximately 1kHz.

Control voltage measured between pins 8 and 5 should be in the range 0 to $0.25V_{cc}$. (It is this voltage divided by R_T which defines capacitor charging current.) Frequency is

$$\frac{2(V_{cc} - V_{control})}{R_T C_T V_{cc}}$$

Further reading
Klein, E. Medium-scale integration for instrumentation and control, *Semiconductors* (Motorola) vol. 2 no. 1 1971, p. 20.
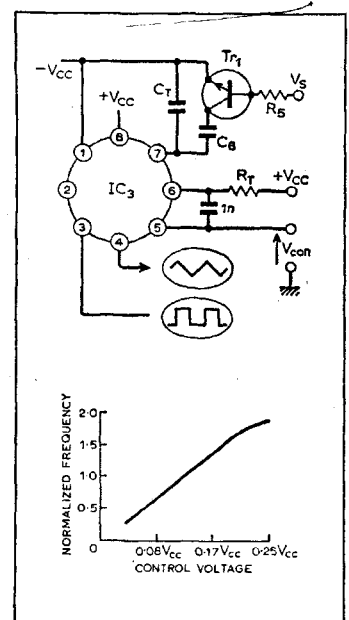
Signetics: SE/NE566 function generator data sheet.

Cross references
Set 17, card 3
Set 8, card 9

Linearized voltage-to-frequency converter

Fig. 2   Fig. 3

Components
R 100kΩ, C 0.22μF
IC 741
Unijunction V-f'_o—see over,
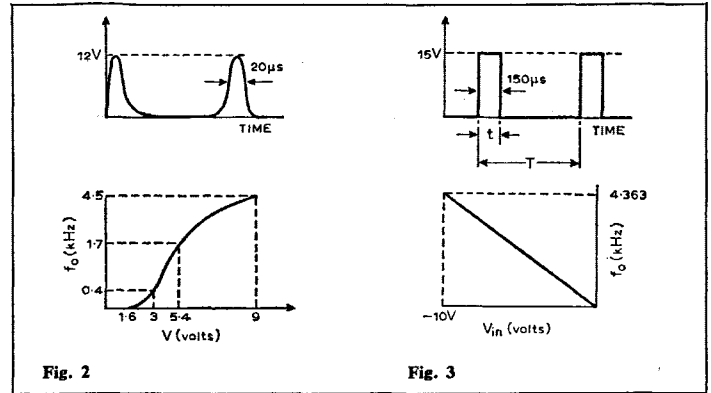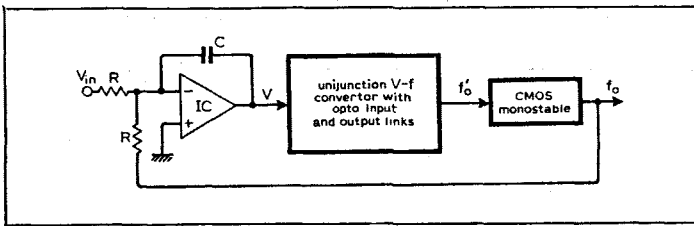centre. Monostable—see over,
right V_{in} 0→−10V

Performance
Graphs of f'_o and f_o are shown
in Figs. 2 and 3. Graph
of V against f_o, corresponding
to open-loop v-f conversion, is
shown in Fig. 2. with V_{in}
against f_o shown in Fig. 3.
Linearity achieved was better
than 0.5%—clearly much better
than the open-loop
performance.

System description
If the loop gain of a closed-loop
system is high then the effect
of non-linearities in the forward
path is much reduced. In this
case we have a highly non-linear
V to f_o converter and an
integrator/error detector is then
included to provide the
feedback. In d.c. terms, the
integrator can be regarded as
having infinite gain since for
finite input voltage the output

voltage after infinite time is
infinite, ignoring the effect of
saturation. Alternatively: $\Delta V =$

$$1/RC \int_0^T V_{in}dt + 1/RC \int_0^t 15dt$$

The steady-state condition of
constant f_o can only occur
when V is constant and this
occurs when ΔV is zero i.e. when
the integral of the input signal
and the integral of the feedback
signal exactly cancel. Hence
exact correspondence between
V_{in} and f_o can be expected if
the integrator and feedback
signal are "perfect". Immediate
improvement in the system
would be effected if an i.c. with
much lower input current
requirements were used e.g.
308. Further improvement
would be obtained by the use
of a low-loss capacitor. The
c.m.o.s. monostable was
included to give an output
pulse train of well defined
height and width and overall
shape. A better f'_o to f_o
converter could have been used.
It should be noted that the
overall characteristics are now
dictated by the feedback signal
and the integrator so that

forward path changes, causing
changes in f_o, will be completely
cancelled, apart from transient
effects. Changes in the shape of
f_o, e.g. impulse height and width,
will however have an effect on
f_o, although not linearity.

System modification
Effectively, the combination of
the monostable and integrator
is an f'_o to v converter. The
system could therefore be
changed to that shown in Fig. 4.
K would be chosen to be
sufficiently high such that the
linearity of the overall system
is equivalent to that of the f to v
converter. This is only
satisfactory if the shape of the
f'_o pulses is satisfactory.

Element description
The circuit of Fig. 5 shows the
detail of the unijunction v to f
converter (card 1) used. The
opto-elements are included to
show that their inherent
isolating properties can be used
not least to produce a very
non-linear v to f'_o characteristic.
This is because D_1 requires
approximately 1.6V to conduct
and there is non-linearity in the

device current transfer ratio.
    Resistor R_2 is
included to protect the
transistor and R_4 is large to
produce a sufficiently large
pulse to trigger the monostable.
Resistor R_1 may be reduced to
allow much lower input
voltages to be used. The limit is
set by the opto-diode input
current. Any opto-isolator
may be used e.g. TIL112.

Components
R_1 2.2kΩ, R_2 1kΩ, R_3 100Ω
R_4 10kΩ
Opto-isolators 4350
(Hewlett-Packard)
U.j.t. 2N2646 V_s 15V
C 0.01μF

Circuit of Fig. 6 is the c.m.o.s.
monostable used. It is identical
in format to that described in
set 18, card 8 but includes an
extra diode to allow the
capacitor to discharge closer
to zero volts to improve
linearity.

Components
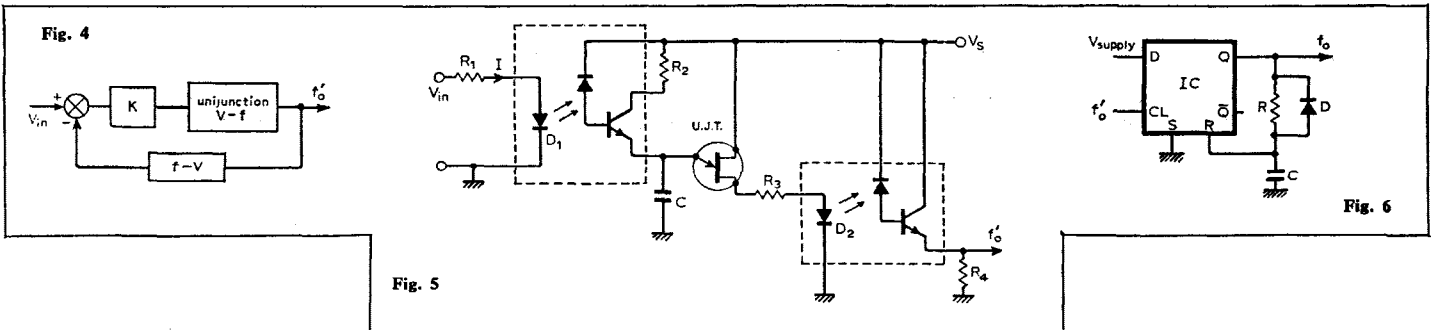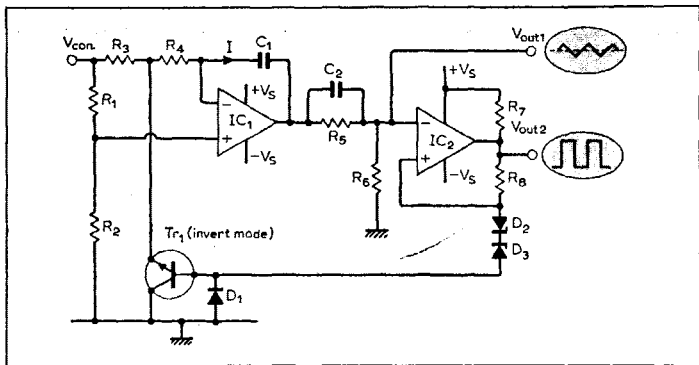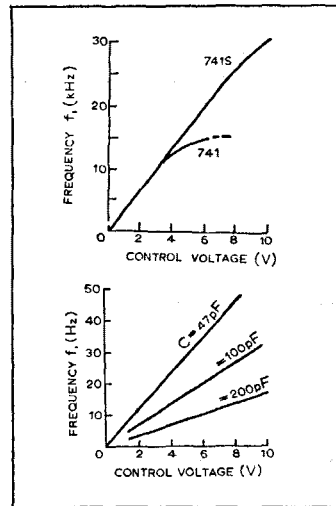R 100kΩ
C 2.2nF
D 1N914
IC CD4013E

Fig. 4

Fig. 5

Fig. 6

Linear voltage-to-frequency converters

Typical performance data
Supply ±15V
IC$_1$ 741S   IC$_2$ LM311
Tr$_1$ ME4002
R$_1$ 68kΩ, R$_2$ 22kΩ, R$_3$ 33kΩ
R$_4$ 15kΩ   R$_5$, R$_7$ 3.3kΩ
R$_6$ 12kΩ   R$_8$ 4.7kΩ all ±5%
C$_1$ 100pF   C$_2$ 1nF
D$_1$ 1N914
D$_2$, D$_3$ reference diodes 6.8V
e.g. BZY88
V$_{control}$ range 0 to 10V
Triangular output ±8V peak
Frequency range 30Hz to 33kHz

Circuit description
The circuit comprises an integrator whose output ramps toward positive and negative target values defined by diodes D$_2$ and D$_3$ i.e. the potential at the non-inverting input of comparator IC$_2$ is V$_{D2}$+V$_{D3}$+ V$_{BC}$ (or V$_{D1}$) about ±9V. When the transistor is off (V$_{o2}$ negative), capacitor current is

$$I = \frac{V_{control}\left(1 - \dfrac{R_2}{R_1 + R_2}\right)}{R_3 + R_4} \quad (1)$$

When Tr$_1$ conducts, I is

$$I = -V_{control}\left(\frac{R_2}{R_1 + R_2}\right)/R_4 \quad (2)$$

For equal slopes at the triangular output, V$_{o1}$, the current magnitudes are equal, provided

$$\frac{R_1}{R_2} = 1 + \frac{R_3}{R_4}$$

If V$_{o2}$ is positive, Tr$_1$ is on, and integrator output rises towards +9V at which level the comparator IC$_2$ switches over to make V$_{o2}$ negative, bringing Tr$_2$ out of conduction. C$_1$ charges according to the first equation, and integrator output ramps towards −9V, when comparator again changes state. Components C$_2$, R$_5$, R$_6$ form a phase-advance network to compensate for the switching delays of IC$_2$ and Tr$_1$ at the higher frequencies. The invert mode of Tr$_1$ provides a very low collector-emitter drop (few millivolts), i.e. the effect on the second equation is neglected. Linearity is better than 0.5% over the range of control

voltage, 0.1V to 8V, based on deviation from 6V value.

Component changes
This slew rate is typically 10V/μs. If 741 used, slew rate (0.5V/μs) restricts higher frequency to which linearity is maintained (see graph).

Range of C$_1$: Typically 47 to 200pF. Frequency variation shown on graphs. Frequency is power supply dependent, hence need for good stability of supply.

Vary mark/space ratio of output at V$_{o2}$ by R$_2$/R$_1$ ratio change; this also modifies frequency.
Range of R$_2$, R$_1$ 22 to 68kΩ
Range of mark/space 1:1 to 1:3.

Circuit modifications
● A variable output voltage is obtainable via the circuit shown in Fig. 1. Comparator hysteresis can be changed by varying the fraction fed back via a potentiometer RV$_1$. This will control the output

amplitude. The triangular output is shaped by the circuit of Fig. 2. Potentiometer RV$_2$ is adjusted for a minimum even-harmonic content, to provide an approximate cisoidal wave form at V$_{out}$.

● The field-effect transistors of Fig. 3 provide a similar switching action to Tr$_1$ in first circuit to provide the integrator capacitor current charging paths. IC$_3$ as an integrator employs a speed-up network of 150pF in series with 10MΩ resistor.
Transistors Tr$_2$ and Tr$_3$ controlled by square-wave output from the Schmitt circuit of IC$_4$. When Tr$_2$ is on, Tr$_3$ is off and C$_3$ charges via Tr$_2$ and 10kΩ resistor. With Tr$_2$ off, and Tr$_3$ on, current reverses through the capacitor with magnitude defined by V$_{control}$/2R$_9$. RV$_3$ should be adjusted to provide a symmetrical square-wave output when V$_{control}$ is 5mV. Input control voltage range: 5mV up to 5V.
Frequency range 10Hz to 10kHz.

Further reading
Wright, M.J. Linear voltage to frequency converter, *Electronic Engineering*, July 1973.
Linearize your v-f converter, *Electronic Design*, Nov. 1973.
Applied Ideas, *Electronic Engineering*, Jan. 1975, p. 17.
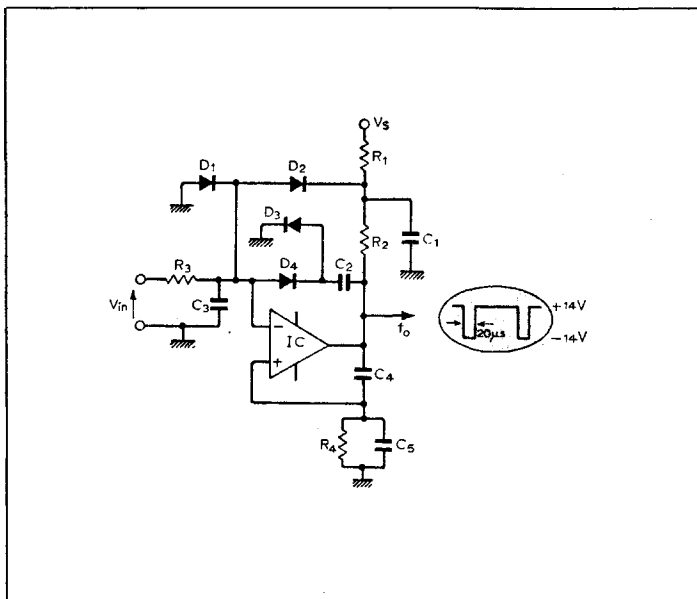Linear Integrated Circuits, National Semiconductor, 1972, p. 255.

Cross references
Set 3, cards 1, 5, 11
Set 17, card 3

Fig. 1
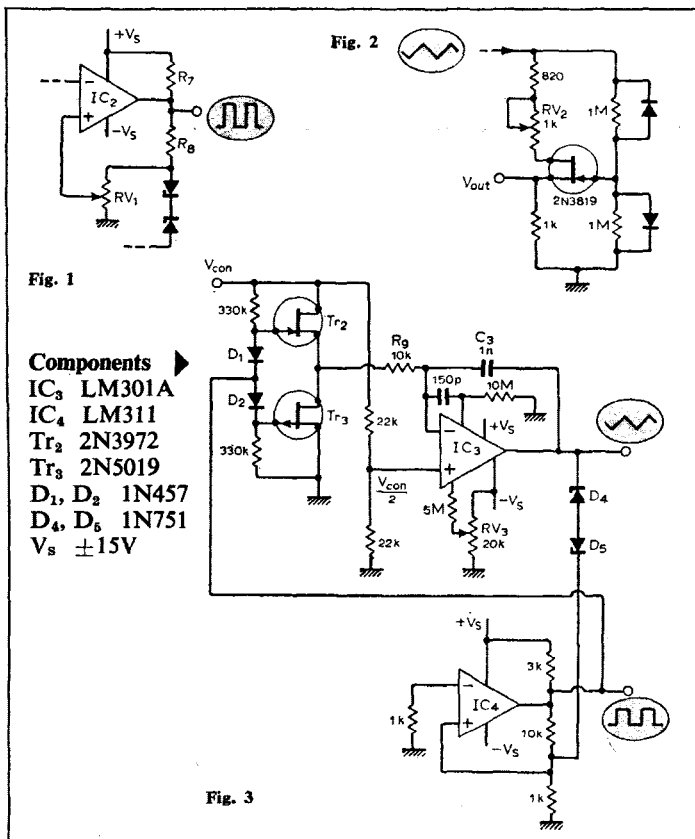
Components ▶
IC$_3$ LM301A
IC$_4$ LM311
Tr$_2$ 2N3972
Tr$_3$ 2N5019
D$_1$, D$_2$ 1N457
D$_4$, D$_5$ 1N751
V$_s$ ±15V

Fig. 3

Diode-pump voltage-to-frequency converter

Components
Supplies ±15V
IC 748C
R_1 12kΩ, R_2 3.9kΩ
R_3 10kΩ, R_4 4.7kΩ
C_1 4.7µF, C_2 1nF
C_3 33µF, C_4 56pF
C_5 500pF
D_1 to D_4 1N914

Performance
V_{in}: 0 to +4.00V
Output pulse train: pulse width
about 20µs swinging from
+14V to −14V with a
maximum frequency of around
14kHz, corresponding to a
mark-space ratio approaching
3:1.
Linearity better than 0.3% over
two decades.

Circuit description
Elements R_1, R_2, D_1, D_2 and
C_1 are not basic to the action
of this circuit and will be
ignored initially. Suppose the
i.c. output is sitting at +14V.
Then C_2 will have been charged
to this level via D_3.
However as C_3 charges via R_3
under the influence of V_{in}, the
negative terminal of the i.c.
eventually reaches 0V and the
amplifier output swings
negative. The network
comprising C_4, R_4 and C_5
provides sufficient positive
feedback to make this swing
very rapid—hence the use of a
high speed op-amp. Capacitor
C_2 then deposits its charge via
D_4 into C_3 in a diode pump
fashion thereby lowering the
voltage across C_3. However the
positive feedback network
consists of elements with a
short time constant and the
voltage on the positive terminal
quickly becomes less negative
than the negative terminal
voltage and so the amplifier
voltage swings back to +14V.
In the −14V period the circuit
is acting rather like a
monostable, the delay being
fixed by the C_4, R_4, C_5 network
and by the R_3, C_3 network.
Because there is again positive
feedback the rising edge will be

equally sharp but the period
will be difficult to define
accurately, partly because of
the complexity of the CR
networks and partly because
two voltages both going in the
same direction (positive) are
being compared.
This, however, is not serious
since the pulse width does not
affect the amount of charge on
C_2, and it is this charge which
is being balanced by the
current in the input network.
The maximum frequency we
obtained was close to the limit
of the op-amp but the mark-
space ratio could have been
made even lower if required by
reducing C_3, R_3 or lengthening
the time constant of C_4, R_4, C_5.
The network comprising R_1,
R_2, C_1 and D_2 prevents the
device from locking into a
saturated condition by too large
an input voltage (positive).
Diode D_1 prevents the negative
input terminal being overdriven
by a negative input voltage.

Circuit modifications
● A high-speed comparator
would be preferable to an
op-amp which was used in our
experiments.

● The pulse width does not
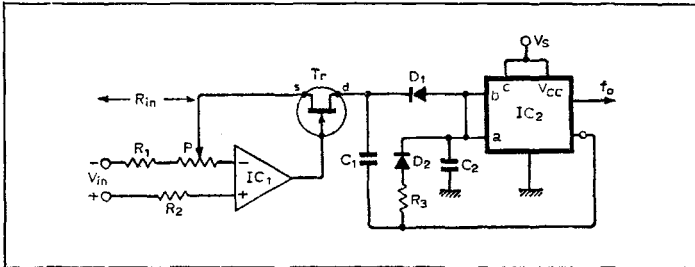theoretically affect the result

but the pulse height does. A
c.m.o.s. buffer amplifier could
be included to give a well
defined output pulse height—
see reference 2.
● An alternative approach to
the pulse height problem is to
use internal clamping of the
output level—see references 3.

References
1 Pease, R. Ultra-linear
   voltage-to-frequency
   converter, *Electronic
   Engineering*, March 1971.
2 Set 3 (waveform generators)
   card 11.
3 Set 3, card 1.
   Set 2, card 1.

Differential input voltage-to-frequency converter

Fig. 2

Fig. 3

Fig. 4

Components
Supplies ±15V
IC$_1$ 741, IC$_2$ NE555
Tr 2N5457
R$_1$ 270Ω
R$_2$ 1.2kΩ
R$_3$ 47Ω
C$_1$ 1nF
C$_2$ 22nF
D$_1$, D$_2$ 1N914

Circuit description

The above circuit is of a form published by Woodward but with what appear to us as corrections, although we have to admit to not achieving the performance claimed in his article, viz linearity better than 0.05% from 10Hz to 10kHz. The results we achieved are shown roughly in Fig. 2, measured linearity being 0.15% over the two decades, 100Hz to 10kHz.

Pin c of IC$_2$ is the R (reset) terminal and its action is not necessary in a brief explanation. Pins a and b are the trigger and threshold terminals of the i.c. When the C$_2$ capacitor voltage goes below the trigger potential, $V_s/3$, the output swings high, and when the voltage exceeds the threshold voltage, $2V_s/3$, the output swings low—see waveforms of Fig. 3.

The basic principle is that of charge dispensing in which a current proportional to a voltage is balanced by the periodic charging of a capacitor to a precise voltage. In this case, the current through the f.e.t. is fixed by the input voltage at V_{in}/R_{in}. This current flows for time T as a result of the charging of C$_2$ from $V_s/3$ to $2V_s/3$. Thus

$$\frac{V_{in}}{R_{in}} \; T = C_2 \frac{V_s}{3}$$

and $$f_0 = \frac{3V_{in}}{R_{in}C_2V_s}.$$

This expression is valid so long as T is large compared with the pulse width.

When the output goes high C$_2$ charges via R$_3$ and D$_2$ from $V_s/3$ toward V_s. During this period D$_1$ is reverse biased and at the same time C$_1$ is providing some current to the f.e.t. When C$_2$ reaches $2V_s/3$ the output goes low, D$_1$ conducts, C$_1$ and C$_2$ share the charge on C$_2$ and the parallel combination discharges linearly through the f.e.t. Diode D$_2$ is reverse biased in this period.

The sharing of the charge between C$_1$ and C$_2$ causes the sharp drop in the C$_2$ voltage when $2V_s/3$ is reached. The discharge is linear because the f.e.t. current is fixed by the input voltage.

The results obtained required adjusting of the op-amp offset voltage to zero. Common-mode rejection ratio is independent of input resistor match and is dictated by the op-amp used. However, common-mode voltage should not exceed ±2V.

Component changes

The charging time depends on C$_2$R$_3$ and should be short without R$_3$ being so low as to overload IC$_2$. This is not difficult to achieve since it is the open collector terminal which is used to charge C$_2$. Capacitor C$_1$ serves to cut off D$_1$ whilst C$_2$ is charging, so its value is not critical. Generally speaking though it should be less than C$_2$ to minimize the drop in C$_2$ voltage when D$_1$ starts conducting again, thereby keeping the slope of the downwards ramp as large as possible and clearly defining the time at which the voltage drops below $V_s/3$. Actually, C$_1$ and D$_1$ can be removed altogether without complete failure of the circuit, although linearity and output pulse shape are affected.

Diodes D$_1$ and D$_2$ can be any general-purpose diodes unless very high speed operation is required.

Reducing the values of the op-amp input resistors and choosing a suitable op-amp will allow values of V_{in} in the millivolt region to be used to give the same output frequencies.

Circuit modifications

Any circuit which will successfully draw constant current from the junction of C$_1$ and D$_1$ will produce the same result and such a circuit is shown in Fig. 4. The photodiode current is proportional to light intensity so an intensity-to-frequency converter would be produced by this arrangement. The differential input aspect is lost, however, unless one puts a second photodiode, connected the opposite way round, across the one shown.

Reference

Woodward, W. S. Simple 10kHz voltage-to-frequency converter features differential inputs, *EDN*, Oct. 20, 1974, p. 86.
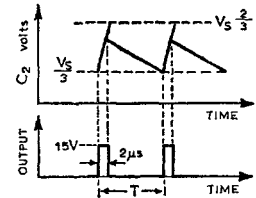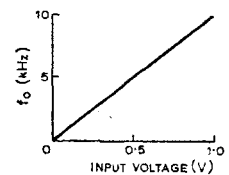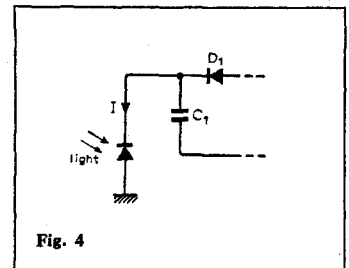
Most of the circuits described have been aimed at linearizing the v-f conversion, as in measurement of modulation systems. Sometimes it is required to have a converter in which the v-f conversion is highly non-linear with the frequency following, for example, an exponential or logarithmic function or sharply changing at some threshold voltage. The circuit indicates a simple way of changing the frequency over a claimed five-decade range.

A linear voltage variation is applied to the base-emitter junction of a transistor to charge a capacitor. The capacitor forms part of an astable circuit based on the well-known 555 timer, with a sawtooth waveform generated across the capacitor swinging between $V/3$ and $2V_s/3$. The reference indicates additional components to set the frequency to zero for $V=0$ and for buffering the output waveform. More generally a linear v-f converter is combined with a non-linear amplifier whose non-linearity is predictable, rather than introducing non-linearity into the conversion process itself.

Reference
Brice, J. L. Voltage-controlled ramp generator, *Wireless World*, June 1976, p. 72.
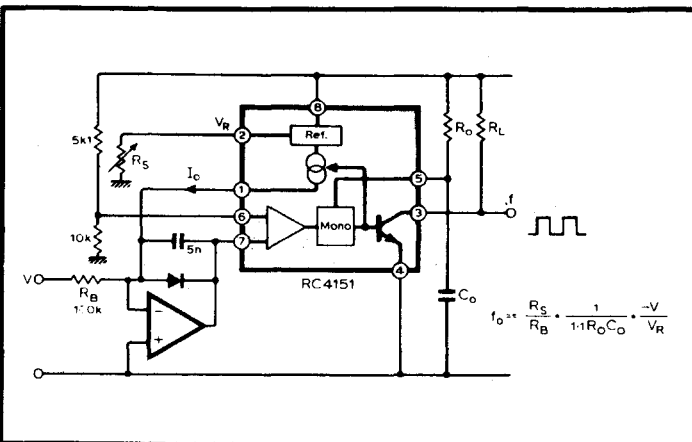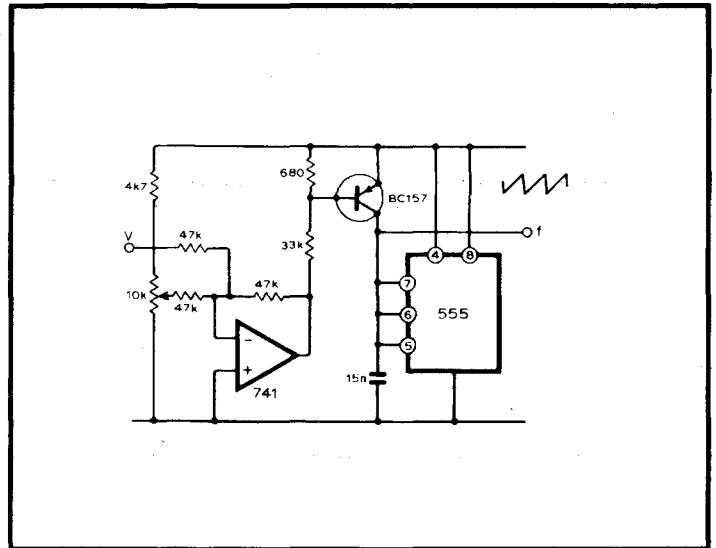
The new generation of linear integrated circuits includes complete v-f modules that will compete with the hybrid and modular versions for many applications. One such monolithic device RC4151 is in line of succession to the 555. It includes a monostable comparator and output stage, but adds a switched current generator. It can be used without additional active devices, but for improved linearity is combined with an op-amp to form a charge-balancing system. The input current to the summing junction is balanced by the constant-height constant-width current pulses returned by the monostable ensuring a linear relationship. A zero-offset voltage fed to the non-inverting terminal ensures that $f\rightarrow0$ as $V\rightarrow0$. Resistor R_s sets the scale-factor for 0–10kHz corresponding to 0→10V.

Reference
Cate, T. IC V-f converters readily handle other functions such as f-V, A-D, *EDN*, Jan. 5, 1977, pp. 82–6.

$$f_o = \frac{R_s}{R_B} \cdot \frac{1}{1 \cdot 1 R_o C_o} \cdot \frac{-V}{V_R}$$

The same article shows amongst other applications a linear thermometer, with some similarity to the band-gap reference circuits of set 23. The temperature-sensing pair are forced to operate at a 10:1 ratio of collector currents giving a ΔV_{BE} that is a controlled linear function of temperature. The precise scaling factor is set by the 5kΩ resistor. The amplifier requires to be a true differential input amplifier of controlled gain. Again the overall function is split into two parts: a linear v-f converter, and a separate circuit to provide the linear or non-linear response. It would be proper to describe this as a T-V-f converter.