Listen to a NEW WORLD OF SOUNDS WITH ULTRASONIC DETECTOR

EXPLORING the world of ultrasonic sound—which lies above approximately 20 kHz—can be exciting and educational. Here is a frequency spectrum beyond human hearing where many insects and rodents communicate with each other, where sounds from leaks in pressurized gas lines occur, etc.

The inexpensive circuits presented here convert these ultrasonic sounds to audio frequencies, enabling anyone to hear them. Also included is a simple ultrasonic transmitter circuit that will enhance your ability to probe this interesting electronics area.

An Ultrasonic Receiver. The schematic diagram of a heterodyne-type ultrasonic receiver is shown in Fig. 1. This receiver hyterodynes ultrasonic signals with those from an internal oscillator, converting them to audible frequencies for reproduction by a dynamic speaker. Thus, it allows you to "hear" any signals it detects.

Piezoelectric transducer TR1 converts ultrasonic waves impinging upon it into ac waveforms which are applied to the noninverting input of operational amplifier IC1A. Because a single-ended power supply is used, resistors R1 and R2 bias the noninverting input to onehalf the supply voltage. Resistor R3, effectively connected across TR1 by electrolytic capacitor C1, damps the transducer's resonant response and broadens its bandwidth. At dc, R5 provides 100% negative feedback to stabilize the operating point. At signal frequencies of interest, the gain of IC1A is 60 dB for the values given in Fig. 1.

REARCE COULD

BY BRIAN DANCE

Inexpensive detector converts ultrasonic sounds from insects, compressed gas leaks, etc., to an audio output.

> The output of *IC1A* is directly coupled to op amp *IC1B*, a similar amplifier stage. The voltage gain of *IC1B*, about 43.5 dB with the component values specified, is somewhat lower than that of the preceding stage. Signals at the output of *IC1B* are capacitively coupled by *C5* to diodes *D1* and *D2*.

> Also applied to the diodes is the output of an ultrasonic oscillator comprising *IC3* and its related components. The frequency of this oscillator is determined by the setting of potentiometer *R12* and the capacitance of *C9*, which is chosen so that the oscillator output corresponds to the resonant frequency of the transducer. (Transducers are readily available from surplus dealers with resonant frequencies ranging from 22 to 44 kHz.)

The two diodes form a nonlinear net-

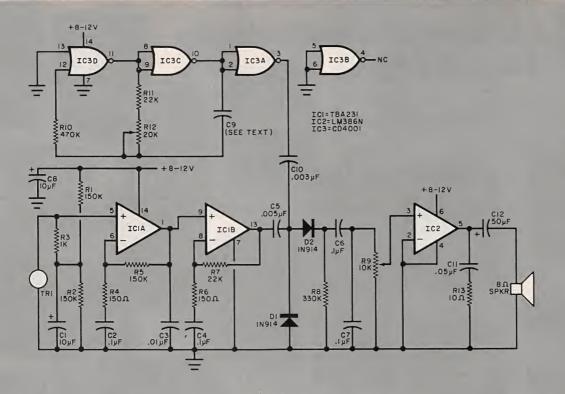


Fig. 1. An ultrasonic receiver, where incoming signals heterodyne with those from the local oscillator to produce an audible output.

C1,C8—10- μ F, 25-V tantalum C2,C4,C6,C7—0.1- μ F disc ceramic C3—0.01- μ F disc ceramic C5—0.005- μ F disc ceramic C9—180-pF (or 330-pF) disc ceramic, polystyrene, glass or silver-mica (see text) C10—0.003- μ F disc ceramic C11—0.05- μ F disc ceramic C12—50- μ F, 25-V electrolytic D1,D2—1N914 signal diode IC1—TBA231 dual op amp (see note)

work. Hence, when signals from the oscillator and the op amp are applied, they heterodyne with each other. If IC3 oscillates at a frequency fairly close to that of an ultrasonic wave detected by TR1, an audible beat signal will appear at the cathode of D2 at a frequency equal to the difference between the two ultrasonic frequencies. The process is similar to that performed in a conventional superheterodyne r-f receiver. The beat note, which can be tuned by adjusting R12, is amplified by IC2, an audio IC, to a level sufficient to drive the dynamic speaker. Potentiometer R9 serves as an audio gain control.

An Ultrasonic Transmitter will help you explore the ultrasonic region more fully. A suitable design is shown schematically in Fig. 2. The circuit is

PARTS LIST FOR FIG. 1

IC2—LM386 audio amplifier IC3—CD4001 quad 2-input NOR gate The following fixed resistors are ¹/4-W, 10% carbon composition: R1,R2,R5—150,000 ohms R3—1000 ohms R4,R6—150 ohms R7,R11—22,000 ohms R8—330,000 ohms R10—470,000 ohms R13—10 ohms

similar to the local oscillator stage in the receiver, but the previously unused fourth gate in the 4001 is employed to provide push-pull drive for transducer *TR2*. The output frequency is variable by means of *R3*. The capacitance of *C1* should be chosen so that the nominal oscillating frequency corresponds to the resonance of the transducer. As was the case with *C9* in the receiver, *C1* should be 180 pF if 44-kHz transducers are used, or it should be 330 pF for use with 22-kHz transducers.

Construction. Either printed circuit or perforated board can be used to duplicate the transmitter and receiver circuits. Parts placement is not especially critical. The use of sockets or Molex Soldercons is recommended when mounting the IC's on the boards. Be sure to R9—10,000-ohm linear-taper potentiometer
R12—20,000-ohm linear-taper potentiometer
SPKR—8-ohm dynamic speaker
TR1—Piezoelectric ultrasonic transducer
Misc.—Printed circuit or perforated board:
suitable enclosure: Hook-up wire; dc
power source; machine hardware; etc.
Note—The TBA231 dual op amp is imported from the U.K. by SG-ATES
Semiconductor Corp., 435 Newtonville,
MA 02160 (Tel: 617-969-1610).

observe normal precautions when handling the CMOS devices. Install polarized capacitors and semiconductors with due regard for polarity and pin basing. Batteries are well suited to power the transmitter and receiver circuits. Note that, when transmitter switch *S1* is in the OFF position, the output states of *IC1*'s gates are frozen. The quiescent current drain of the circuit is so small that no power switch is necessary. If a battery supply is used with the receiver, however, an spst power switch should be used to disconnect the circuit from the supply when it is not being operated.

Use. Receiver potentiometer *R12* tunes the circuit across a limited portion of the ultrasonic frequency range. Apply power and adjust audio gain control *R9* until some noise is heard through the speaker. Then rub the palms of your hands in front of *TR1*. The receiver will detect the ultrasonic energy from the rubbing.

You will notice that *TR1* has a very directional response. This is due to the fact that ultrasonics have very short wavelengths (compared to those at audio frequencies) and are thus subject to less diffraction at the edges of large objects. Also, ultrasonic waves behave like light waves in that they tend to travel in straight lines.

It's interesting to note that if coupling capacitor *C10* in the receiver is disconnected from the diode mixer, the receiver will still detect ultrasonic signals if more than one frequency is present. The frequencies present at the input will beat against each other to produce an audible output. This can be verified by repeating the palm-rubbing experiment described earlier after the coupling capacitor has been disconnected. The speaker will still generate an audio output even though no local oscillator signal is being injected into the diode mixer.

If an ultrasonic wave generated by transmitter transducer *TR2* now impinges upon *TR1*, the random noise reproduced by the speaker will drop to a low level. No tone will be heard because only one frequency is applied to the mixer. Stray coupling that allows a portion of the local oscillator output to reach the mixer will create an audible beat.

When the receiver and transmitter are operating in the same room, a signal will be heard as *R12* tunes the receiver across its range. The two transducers do not *have* to be directly facing each other if enough hard surfaces in the room reflect the ultrasonic waves, and the room is not so large that it introduces excessive signal attenuation.

The circuits presented have been successfully used with ultrasonic transduc- . ers from many different sources, including those used in television receiver remote control accessories. Of course, if you want to tune in several ultrasonic "bands," you can use a multiple-pole rotary switch to select the appropriate transducer and its corresponding oscillator capacitance. Experimentation indicates that the receiver can "hear" the transmitter at distances up to 125 feet if the transducers are aimed at each other. The use of a suitable parabolic reflector in tandem with TR1 and/or multiple driven transmitter transducers should result in even greater useful range.

Other Suggestions. We have already mentioned the possibility of using these circuits for signalling purposes. Many other practical applications exist. For example, leaks in the rubber sealing of car doors and windows or in the sealing of a freezer door. The transmitter is placed in the car or freezer and fills the interior with ultrasonic waves. The walls of the interior reflect the waves to create a wide dispersion of ultrasonic energy. If the receiver's transducer is moved over the exterior, a tone will be heard whenever it passes any leaks. ♢

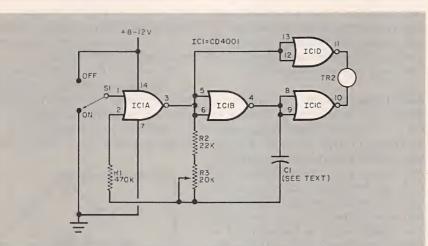


Fig. 2. This ultrasonic transmitter employs four NOR gates.

PARTS LIST FOR FIG. 2

C1—180-pF (or 330-pF) disc ceramic, polystyrene, glass or silver mica capacitor
IC1—CD4001 quad dual-input NOR gate
R1—470,000-ohm 10%, ¹/₄-W resistor
R2—22,000-ohm 10%, ¹/₄-W resistor
R3—20,000-ohm linear-taper potentiometer S1-Spdtswitch

TR2—Piezoelectricultrasonic transducer Misc.—Printed circuit or perforated board; suitable enclosure; hook-up wire; dc power source; machine hardware, etc.

SURFER

(Continued from page 116)

good choice is a 4" to 6" (10.2 to 15.2 cm) high-compliance, high-fidelity quality 8- or 16-ohm speaker.

With Q1 operated in the manner shown, it is susceptible to detecting r-f. Hence, the circuit should be housed in a metal box and the common bus on the pc board electrically connected to the box. The pc board assembly mounts in place with spacers and machine hardware. POWER switch S2, VOLUME control R12, INTERVAL control R20, and SELEC-TOR switch S1 mount on the front panel. Transformer T1 and the holder for fuse F1 can be mounted on the rear of the box. The line cord should enter the box through a grommet-lined hole.

Adjustment and Operation. Two simple adjustments are required to get the Surfer into proper operating order. Set trimmer pots *R9* and *R16* to their centers of rotation, set the VOLUME control fully clockwise (maximum volume), and set *S1* to the SURF position. Now, apply power and set the INTERVAL control for a period of about 25 seconds. Adjust *R16* so that *I1* extinguishes about a second before the end of the cycle. Wait several cycles and then check *R16* again and readjust it if necessary. Once *R16* is adjusted, place the shield over the lamp/photocell assembly.

Set the VOLUME control to its center of rotation. Then adjust trimmer pot *R9* until the sound is just barely audible at the beginning of the cycle.

During operation, when S1 is set to SURF, C5 (see Fig. 1) produces the maximum high-frequency rolloff and PC1 is connected to the base of Q3. This produces a roaring sound that changes in intensity and tone. In the RAIN position of S1, maximum high-frequency attenuation occurs with no amplitude modulation. This creates a constant-volume "hiss" whose tone varies. When S1 is in the NOISE position, R11 is shorted out, which causes the tone control to lose its effectiveness. In general, a long interval is best for the SURF function, while a short interval is best for RAIN.

The Surfer is not intended to be used as a sound-effects generator to which one consciously listens. Rather, it is meant to provide a nondistracting background of sounds. Best effects are created when the Surfer is positioned 6' (1.8 m) or more from the listener with the volume adjusted so that the sound is barely audible.