

Reducing the dropout voltage of programmable regulators

by Carlo Venditti
The Charles Stark Draper Laboratory Inc., Cambridge, Mass.

A programmable regulator's dropout voltage—the minimum allowable potential between its input (V_{in}) and output (V_{out})—can be improved by adding an external output stage and negative feedback. The resulting regulated output voltage (E_{out}) not only approaches V_{in} more closely, but the current-drive capability is also better, thanks to the outboard power-transistor stage.

The design technique used to achieve this improved performance is described here for Fairchild's popular $\mu A78MG$ regulator, which has a nominal dropout voltage of 3.0 volts. As shown in the figure, a change in V_{in} causes V_{out} to increase temporarily. The corresponding increase at E_{out} that is applied to the control input of the $\mu A78$ forces V_{out} lower, toward the value it had initially. If the resistor network R_1 to R_3 is optimized, E_{out} can be brought to within 1.5 V of V_{in} .

Consider the case where the output voltage E_{out} is to be kept at $12.5 \text{ v} \pm 50 \text{ mv}$ for a V_{in} ranging from 14 to 15.5 v. When V_{in} is at 14, V_{out} cannot be above 11, owing to the dropout voltage of the regulator. Thus with an output voltage of 12.5, the voltage at the base of Q_1 is 13.1 (0.6 v higher).

Now R_1 can be selected to pass a given value of

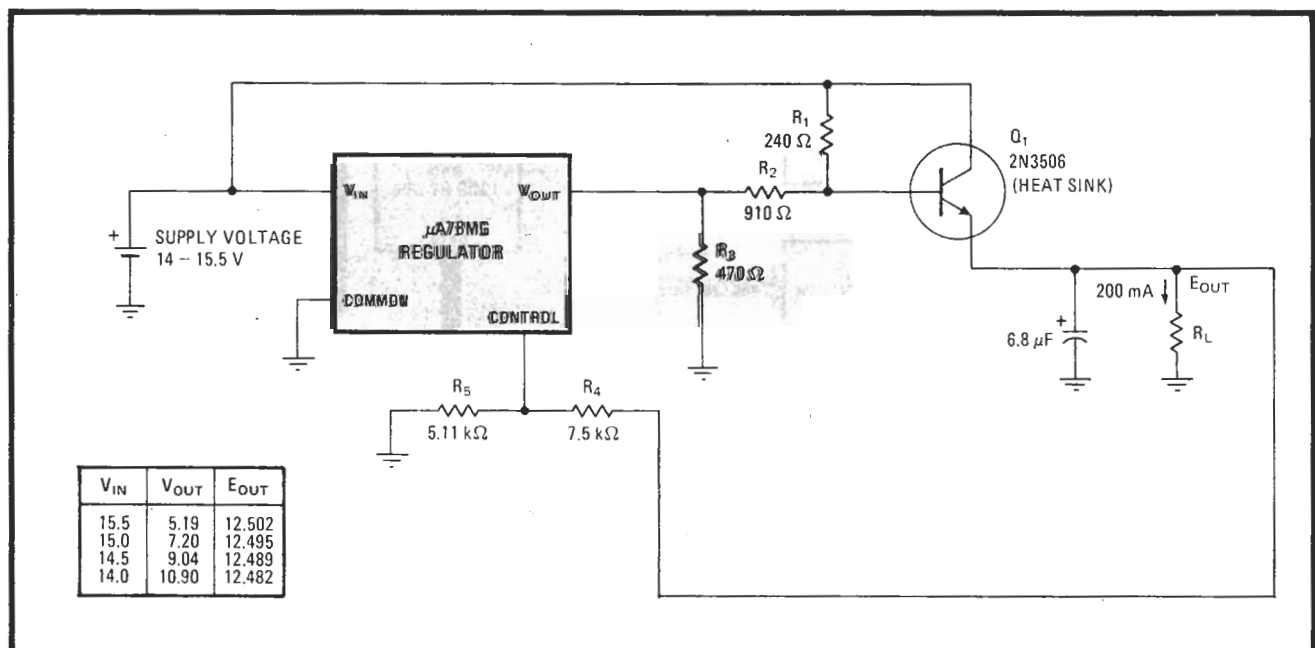
transistor base current, I_b , of say, 1.2 milliamperes, and a current through R_2 of perhaps twice this value (2.4 mA), plus a small amount to account for variations in I_b . Thus $R_1 = (14 - 13.1) \text{ v} / 3.75 \text{ mA} = 240 \Omega$, and $R_2 = (13.1 - 11) \text{ v} / 2.4 \text{ mA} = 910 \Omega$.

The next condition to be addressed is the case where V_{in} assumes a value of 15.5 v, so that R_3 may be determined. Because V_{out} ultimately decreases with an increase in V_{in} , V_{out} should be made to move to its minimum value so that the maximum dynamic range of the circuit is realized. From the data sheet of the $\mu A78$, $V_{out(\text{min})} = 5.0 \text{ v}$. Note that changes in V_{out} are scaled by the R_2/R_1 ratio, and these resistors ensure that a change of $910/240 = 3.8 \text{ v}$ occurs for every 1-v increase in V_{in} .

Thus the current through R_2 at this time will be $(13.1 - 5.0) / 910 = 8.8 \text{ mA}$, and assuming the minimum (quiescent) current of the regulator is 2 mA, the current through R_3 is $(8.8 + 2.0) = 10.8 \text{ mA}$. Therefore $R_3 = 5 / 10.8 = 470 \Omega$. The table summarizes the actual dynamic performance of the regulator. Note the apparent dropout voltage of the regulator has been reduced to $14.0 - 12.482 \approx 1.5 \text{ v}$ when V_{in} is at its minimum.

The junction temperature of the on-chip power transistor is $T_j = \theta_{JA} P_T + T_A$, where θ_{JA} is the junction to ambient thermal resistance (80 Ω , see data sheets) and T_A is the ambient temperature. Thus, assuming $T_A = 25^\circ\text{C}$, $T_j = 35^\circ\text{C}$, well below the 125°C thermal shutdown temperature of the $\mu A78$.

A check on the chip's temperature will confirm that the regulator's thermal shutdown point has not been reached. The temperature reaches a maximum when $V_{in} = 14.0$. At this voltage, the regulator's output current is



Closer. Outboard power transistor stage, and resistor pad R_1 – R_3 set E_{out} to within a few volts of V_{in} , so that $(E_{out} - V_{in})$ is below $\mu A78$'s dropout value. Q_1 also provides increased current capacity. Table summarizes dynamic range attained for example using technique discussed in text.

20.8 mA, and the output power is $20.8 (14 - 11) = 62.5$ mW. The quiescent current is 4 mA (see data sheets), and the quiescent power drain becomes $4(14 \text{ V}) = 56$ mW. As a consequence of these figures, the total output becomes $P_T = 118$ mW. □
