

# High-side, bidirectional current-sensing circuit with transient protection

### **Design Goals**

Input		Out	put	Supply		Standoff and Clamp Voltages		EFT Level	
I <sub>inMin</sub>	I <sub>inMax</sub>	V <sub>oMin</sub>	$V_{oMax}$	Vs	GND	V <sub>ref</sub>	Vwm	Vc	Vpp
-40A	40A	100mV	4.9V	5V	0V	2.5V	36V	80V	2kV 8/20µs

### **Design Description**

This high-side, bidirectional current sensing solution can accurately measure current in the range of -40A to 40A for a 36-V voltage bus. The linear voltage output is 100mV to 4.90V. This solution is also designed to survive IEC61000-4-4 level 4 EFT stress (Voc = 2kV; Isc = 40A; 8/20µs).



### **Design Notes**

- 1. This solution is targeted toward high-side current sensing.
- 2. The sense resistor value is determined by minimum and maximum load currents, power dissipation and Current Shunt Amplifier (CSA) gain.
- 3. Bidirectional current sensing requires an output reference voltage (Vref). Device gain is achieved through internal precision matched resitor network.
- 4. The expected maximum and minimum output voltage must be within the device linear range.
- 5. The TVS diode must be selected based on bus voltage, the CSA common-mode voltage specification, and EFT pulse characteristics.

### **Design Steps**

1. Determine the maximum output swing:

VswN = Vref - VoMin = 2.5V - 0.1V = 2.4VVswP = VoMax - Vref = 4.9V - 2.5V = 2.4V

2. Determine the maximum value of the sense resistor based on maximum load current, swing and device gain. In this example, a gain of 20 was chosen to illustrate the calculation, alternative gain versions may be selected as well:

 $\text{Rshunt} \leq \frac{\forall \text{swp}}{\text{lin}\_\text{max} \times \text{Gain}} = \frac{2.4 \forall}{40 A \times 20} = 3 \text{m} \ \Omega$ 

3. Calculate the peak power rating of the sense resistor:

 $Pshunt = Iin_max^2 \times Rshunt = 40A^2 \times 3m \Omega = 5W$ 

- 4. Determine TVS standoff voltage and clamp voltage: Vwm = 36V and  $Vc \le 80V$
- 5. Select a TVS diode.

For example, SMBJ36A from Littelfuse<sup>™</sup> satisfies the previous requirement, with peak pulse power of 600W (10/1000µs) and current of 10.4A.

6. Make sure the TVS diode satisfies the design requirement based on the TVS operating curve.

Peak pulse power at given excitation (8/20 $\mu s$ ) is estimated to be around 3.5kW, which translates to peak pulse current:

 $Ipp = \frac{3.5kW}{600W} \times 10.4A = 60A$ 

This is above the maximum excitation (short circuit) current of 40A. The select TVS effectively protects the circuit against the specified EFT strike.



### Design Simulations





### **Transient Simulation Results**

The output is a scaled version of the input.





### **TVS Diode Transient Response Under EFT Excitation**



### **Design References**

See Analog Engineer's Circuit Cookbooks for TI's comprehensive circuit library.

For more information on transient protection of the current sense amplifiers, see TIDA-00302 and the Current Sense Amplifier Training Videos.

### Design Featured Current Sense Amplifier

INA240A1				
Vs	2.7V to 5.5V			
V <sub>CM</sub>	-4V to 80V			
V <sub>os</sub>	Rail-to-rail			
V <sub>os</sub>	5μV			
I <sub>B</sub>	80μΑ			
BW	400kHz			
Vos Drift	50nV/°C			
http://www.ti.com/product/INA240				

### **Design Alternate**

INA282				
V <sub>s</sub>	2.7V to 18V			
V <sub>CM</sub>	-14V to 80V			
V <sub>os</sub>	20µV			
I <sub>B</sub>	25μΑ			
BW 10kHz				
Vos Drift 0.3µV/°C				
http://www.ti.com/product/INA193				

### **Revision History**

Revision	Date	Change
A	February 2019	Changed VinMin and VinMax in the Design Goals table to linMin and linMax, respectively.



### Analog Engineer's Circuit: Amplifiers

SBOA310A-December 2018-Revised February 2019

## High-side current-sensing circuit design

### **Design Goals**

Inț	out	Out	tput	Supply	
I <sub>iMin</sub>	l <sub>iMax</sub>	V <sub>oMin</sub>	V <sub>oMax</sub>	V <sub>cc</sub>	V <sub>ee</sub>
50mA	1A	0.25V	5V	36V	0V

### **Design Description**

This single-supply, high-side, low-cost current sensing solution detects load current between 50mA and 1A and converters it to an output voltage from 0.25V to 5V. High-side sensing allows for the system to identify ground shorts and does not create a ground disturbance on the load.



### **Design Notes**

- 1. DC common mode rejection ratio (CMRR) performance is dependent on the matching of the gain setting resistors, R<sub>2</sub>-R<sub>5</sub>.
- 2. Increasing the shunt resistor increases power dissipation.
- 3. Ensure that the common-mode voltage is within the linear input operating region of the amplifier. The common mode voltage is set by the resistor divider formed by R<sub>2</sub>, R<sub>3</sub>, and the bus voltage. Depending on the common-mode voltage determined by the resistor divider a rail-to-rail input (RRI) amplifier may not be required for this application.
- 4. An op amp that does not have a common-mode voltage range that extends to  $V_{cc}$  may be used in low-gain or an attenuating configuration.
- 5. A capacitor placed in parallel with the feedback resistor will limit bandwidth, improve stability, and help reduce noise.
- 6. Use the op amp in a linear output operating region. Linear output swing is usually specified under the A<sub>OI</sub> test conditions.

### **Design Steps**

- 1. The full transfer function of the circuit is provided below.
  - $$\begin{split} V_o &= I_{in} \times R_1 \times \frac{R_5}{R_4} \\ & \text{Given} \quad R_2 &= R_4 \quad \text{and} \quad R_3 &= R_5 \end{split}$$
- 2. Calculate the maximum shunt resistance. Set the maximum voltage across the shunt to 100mV.  $R_1 = \frac{V_{Max}}{I_{Max}} = \frac{100mV}{1A} = 100m\Omega$
- 3. Calculate the gain to set the maximum output swing range.  $Gain = \frac{V_{oMax} - V_{oMin}}{(I_{Max} - I_{Min}) \times R_1} = \frac{5V - 0.25V}{(1A - 0.05A) \times 100m\Omega} = 50\frac{V}{V}$
- 4. Calculate the gain setting resistors to set the gain calculated in step 3.

Choose  $R_2 = R_4 = 1.01 k \Omega$  (Standard value)  $R_3 = R_5 = R_2 \times Gain = 1.01 k \Omega \times 50 \frac{V}{V} = 50.5 k \Omega$  (Standard value)

5. Calculate the common-mode voltage of the amplifier to ensure linear operation.

$$V_{cm} = V_{CC} \times \frac{R_3}{R_2 + R_3} = 36V \times \frac{50.5k}{1.01k + 50.5k} = 35.294 V$$

6. The upper cutoff frequency (f<sub>H</sub>) is set by the non–inverting gain (noise gain) of the circuit and the gain bandwidth (GBW) of the op amp.

$$f_{H}\!=\!\frac{GBW}{Noise\,Gain}\!=\!\frac{10MHz}{51_{V}^{V}}\!=196$$
 . 1  $\,$  kHz

TEXAS INSTRUMENTS

### www.ti.com

### **Design Simulations**

**DC Simulation Results** 









### **References:**

- 1. Analog Engineer's Circuit Cookbooks
- 2. SPICE Simulation File SBOMAV4
- 3. TI Precision Labs

### Design Featured Op Amp

OF	PA192	
V <sub>cc</sub>	4.5V to 36V	
V <sub>inCM</sub>	Rail-to-rail	
V <sub>out</sub>	Rail-to-rail	
V <sub>os</sub>	5µV	
l <sub>q</sub>	1mA	
I <sub>b</sub>	5pA	
UGBW	10MHz	
SR	20V/µs	
#Channels	1, 2, 4	
www.ti.com/product/OPA192		

### **Design Alternate Op Amp**

OPA2990				
V <sub>cc</sub>	2.7V to 40V			
V <sub>inCM</sub>	Rail-to-rail			
V <sub>out</sub>	Rail-to-rail			
V <sub>os</sub>	250µV			
l <sub>q</sub>	120µA			
I <sub>b</sub>	10pA			
UGBW	1.25MHz			
SR	5V/µs			
#Channels	2			
www.ti.com/product/OPA2990				

### **Revision History**

Revision	Date	Change
A	February 2019	Downstyle title. Added Design Alternate Op Amp table.