

number of teeth decides the *step angle* and the number of steps per revolution. In the absence of any electrical input, the rotor will lock to the stator by seeking out paths of minimum magnetic reluctance.

There are normally two groups of windings provided. The "A" winding is active one-third of the distance between teeth, while the "B" winding is active two-thirds of the distance between the teeth.

In typical use, a four-step process is used to advance to the next tooth position. The A winding first gets activated, attracting the toothed rotor one-third of the distance to the next tooth. Then the B winding is activated, attracting to the two-thirds point. Next, the A winding has its current reversed to further repel towards that two-thirds point. In the final step, that current in the B winding gets reversed, repelling the rotor to its new and final position.

The speed gets determined by the number of steps applied per second. The direction is set by changing the roles of the A and B windings.

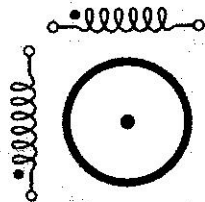


FIG. 1—IN A BIPOLAR (OR UNIFILAR) stepper motor, there is only a single grinding for each phase. Although the stepper itself is powerful and low-cost, the driver circuitry gets extra complicated, since a full-bridge circuit is needed—one that is able to send current in either direction. Bipolar stepper's often have four leads.

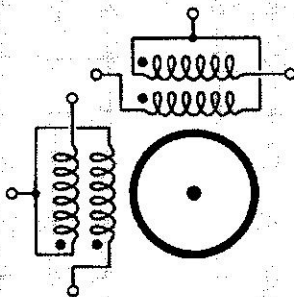


FIG. 2—IN A UNIPOLAR (OR BIFILAR) stepper motor, you will find a pair of windings for each phase. While that raises the cost and also reduces the available stepper power, your driver circuitry is far simpler and very much cheaper, since only a current sink is needed for each winding. A unipolar stepper often has six leads.

Other patterns of activating the A and B windings might give you various speed and torque options, as well as actually *microstepping*, the moving to a precise position *between* the rotor teeth.

As Figs. 1 and 2 show us, there are two different methods with which stepper motors are commonly wound. In a *bipolar* stepper there is only a single A winding and only a single B winding. That is cheaper and has more power, but requires you to electronically *reverse* the high current through both windings. Thus, what you gain in stepper economy, you lose in driver complexity.

In a *unipolar* or a *bifilar* stepper, there are two distinct A windings and two separate B windings. Each of the windings go in the opposite sense of the other, so a current in one winding will attract the rotor, while the same current in the other winding will instead repel the rotor. The unipolar windings are much easier to drive, but they

cost more and offer less power.

You can usually tell which type of stepper you have by the number of leads. Assuming that all the leads are brought out separately, a bipolar stepper will have four wires, while a unipolar one will have six. For most hacker uses, the unipolar and bifilar windings are the best choice, since they are easier and cheaper to drive.

Good data sheets and ap-notes on steppers are available from *Airpax*, *Hayden*, *Superior Electric*, and most of the other suppliers. Bunches of technical articles and supplier ads for steppers appear in the *PCIM* and *Motion* trade journals, as well as the usual electronics insider magazines.

While new steppers are usually rather pricey, you can find lots of surplus ones in assorted sizes and voltages for as little as \$2 through all the usual **Radio-Electronics** ads and similar surplus sources.

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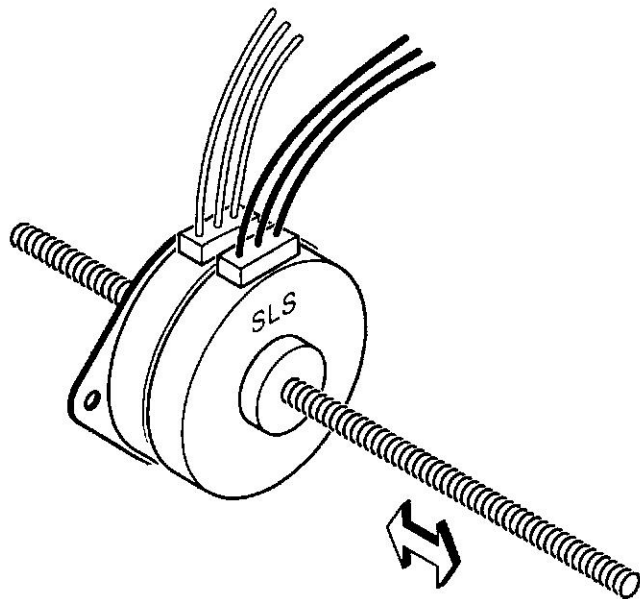


FIG. 3—THE HURST SLS LINEAR ACTUATOR is a real "sleeper" for hardware hacking. This easy-to-drive 12-volt, 12-watt unit offers 24 pounds of force in 2-mil (0.002) increments. What can you do with it that's new and really different?

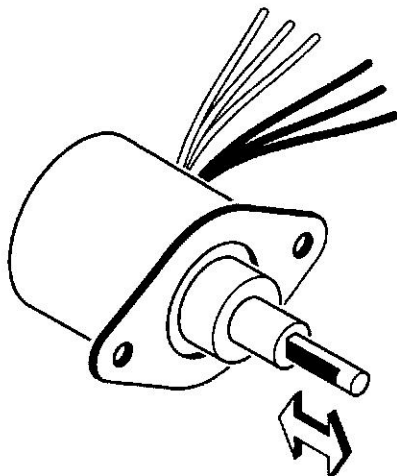


FIG. 4—THE AIRPAX 92100 is a smaller linear stepper motor having a 1/2-inch stroke. Similar units may be available at a junkyard as throttle idle controllers.

about cotton picking, what we have here is an easy and precise way to eliminate a most tedious and time-consuming job. If the teeth are too close, you destroy the machine. If they are too far away, your yield and your grade goes down.

A third source of linear actuators is *Eastern Air Devices*, but their military look and their refusal to include pricing in their mailings does not bode well for hackers.

Stepper drivers

Most of the stepper manufacturers have available driver circuit-

ry for their devices, but those tend to be older hybrids that seem overpriced. Instead, there are several suppliers of single- and double-chip stepper-motor drivers. They include *Sprague*, *SGS*, and *Motorola*.

Figure 5 shows you a circuit for the *Sprague* UCN-4204B single-chip stepper driver. While I haven't yet been able to check the chip out (stay tuned), it looks like a typical modern circuit with 1.5 amps of drive capability and inter-

nal protection for both overheating and overcurrent. They are well under \$4 in singles.

To use the circuit, you provide two inputs. The first is the direction input which decides whether your stepper will spin forward or backward. The second is a train of square-wave pulses that sets the speed in the chosen direction.

It is usually best to computer control your stepper driver. As we've seen, an otherwise unused Commodore 64 is ideal for that sort of thing, and their going rate is around \$30 at a yard sale.

One microcontroller chip that I really like which includes dual low-level stepper drivers on-chip (among lots of other goodies) is the great M50734 by *Mitsubishi*. That dude cross-assembles beautifully on an Apple IIe or IIgs.

Three contests

Let's have three contests this month. There will be the usual *Incredible Secret Money Machine* prizes for the best dozen entries, with an all-expense paid (FOB Thatcher, AZ) *tinaja quest* for two going to the very best of all.

For the easy contest, just tell me something you would like to do with a linear stepping motor or a linear actuator. Or two or even three. Especially if they have twenty pounds of force in 2-mil increments.

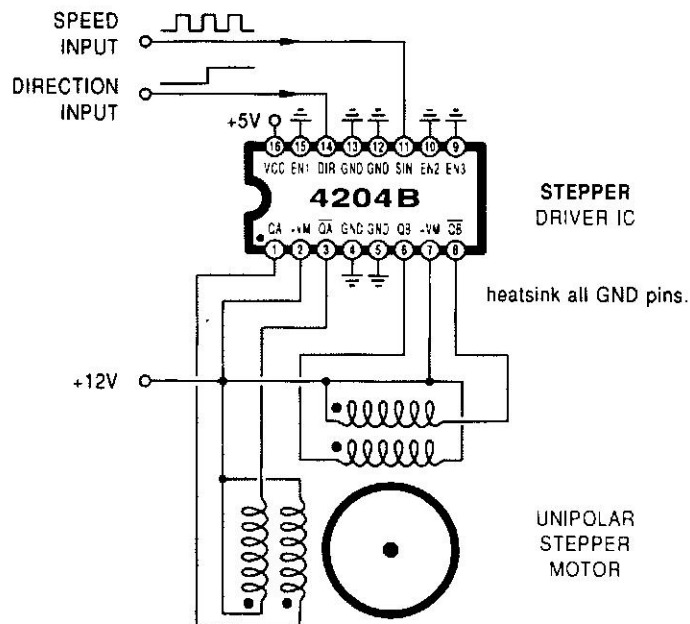


FIG. 5—LOW-COST SINGLE-CHIP stepper-motor drivers are readily available from Motorola, SGS, and Sprague, among others. Here's a popular Sprague driver.

Edmund Scientific

101 E. Gloucester Pike
Barrington, NJ 08007
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Kirkland, WA 98034
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(312) 299-2222

Fine Scale Modeling

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(414) 796-8776

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Rogers, MN 55374
(612) 428-2899

Two linear steppers

Take an ordinary stepper motor, but make it hollow at its center. Then add a threaded shaft through the middle, which gets driven from a nutplate on the stepper armature. As the stepper is stepped, the nutplate turns, which in turn advances or retards the threaded shaft.

All of which gives you a way to push or pull things in tiny and very accurate increments under computer control. With lots of force over fairly long strokes.

Uses? Animation tables, printed-circuit drills, a numeric-controlled milling machine, plotters, robotics, valve actuators, electronic engine controls, research projects, point-of-purchase displays, plus dozens of uses previously unthunk of.

Figure 3 shows you the *Hurst* model SLS linear actuator. It's a 12-watt unit that gives you 25 pounds

of force in 2-mil (0.002 inch) increments, over an 8-inch actuating length.

While under \$20 in quantity, single evaluation units cost around \$55, unless you can locate a surplus one. That seems rather high, until you take that "Uh, compared to what?" factor into account.

On custom order, lead screws up to several feet long can be obtained. Note that there is no theoretical limit to the stroke you could get out of one of those, so long as a lead screw that length is available. Maintaining the precision and avoiding any binding would, of course, get far worse with increasing length.

Figure 4 shows you a smaller *Airpax* series 92100 unit. They are much smaller and give you a half-inch maximum stroke, in 2- or 4-mil steps, having a force slightly over one pound.

The price is around \$25 each,

but you might be able to find one nearly free at your local junkyard, as some automobiles use them for computerized carburetor idle adjustments. Unfortunately, I don't know which specific models to send you after. There are also some plain old throttle solenoids that look just about the same, so make sure you are getting a "real" stepper when you make your visit.

You can step them up to 400 steps per second, which means you can travel the half-inch stop-to-stop distance in something like 0.6 seconds. But you do lose force at the higher stepping rates.

We're using that one locally to adjust the teeth on a cotton picking machine. The stepper acts as sort of a micrometer, advancing until it touches each tooth. The number of steps needed then tells the mechanic how much shim to add.

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For our intermediate contest, just tell me which makes and models of automobiles use linear stepping actuators as their idle controls.

For the hard contest, nobody talks very much about the electrical and mechanical *efficiency* of a stepping motor. *Why?* Could a very large and extremely efficient linear stepping motor be built?

That would dramatically improve solar water-pump design, as the pump stroke and speed could be exactly and continuously matched to both the available input solar power and the well characteristics. Which might enormously simplify and cheapen both the electronic and mechanical designs. Especially for remote and third-world applications.

Modelmaking resources

In any large electronics company, the model shop is that secret

lair where all of the mockups, mechanical prototypes, breadboards, concept pieces, and one-of-a-kinds come from. As a hacker, you are your own model shop, so it is super important to know where to go to get all of the non-electronic bits and pieces you'll need to make hacking more hackable. Our new Modelmaking Resources sidebar shows you a few places to go for model info and supplies.

Naturally, you will want to check out your own local resources first. Those should include a good hardware store, a large junkyard, a real hobby shop, and a few electronic surplus houses that do not have a catalog and do not advertise in any national magazines. One regional example around here is the *Apache Reclamation and Salvage*. Ask any ham radio operator for a complete neighborhood list.

I've also found a local horse-trailer factory to be useful, es-

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(203) 756-7441

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PO box 217
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(616) 982-3789

Hurst Manufacturing

Box 326
Princeton, NJ 47670
(812) 385-2564

Linear Technology

1630 Mc Carthy Blvd.
Milpitas, CA 95035
(408) 432-1900

Mitsubishi

1050 East Arques Avenue
Sunnyvale, CA 94086
(408) 730-5900

Motion Magazine

Box 6430
Orange, CA 92613
(714) 974-0200

Motorola

5005 E. McDowell Rd.
Phoenix, AZ 85008
(602) 244-6900

PCIM

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