

Multi-channel Tone Control

A five-channel unit using active band-pass filters

by J. R. Emmett*, B.Sc.

New ideas in tone controls have appeared in the last few years^{2,3} which improve or supplement bass and treble controls, which are usually of the Baxandall type.¹ If the function of these controls is clearly understood, a fairly flexible amplitude frequency response curve can be built up. However, an easier and more versatile method of building a desired response is to use a number of overlapping, variable gain, frequency channels, spaced evenly throughout the audio spectrum. By using linear slider potentiometers, the control panel presentation can be made to resemble a response against frequency graph. In this form the system is sometimes called a "graphic equalizer". The unit which will be described for construction has five channels with centre frequencies of 50Hz, 200Hz, 800Hz, 3.2kHz and 12.8kHz. The linear slider potentiometers used give a control range of ± 12 dB. The designed signal level for normal use is around 0dBm (approximately 800mV), a level matching most modern amplifier and recording equipment inputs.

Negative feedback system

The usual method of obtaining a multi-channel response is by using an LC band-pass filter and gain control for each channel. The range of inductance needed to cover the ten octaves or so of the audio band makes the filters expensive and unattractive. In addition, much trimming is normally needed to obtain a basically flat response, due to crossover interactions between channels.

Negative feedback methods offer many advantages, such as reduced noise and distortion and accurate gain setting using potentiometers of linear law. In the case of the multichannel system, the filter specification may be greatly relaxed, and trimming can normally be eliminated.

A block diagram of this type of system is given in Fig. 1. At the centre frequency of a channel, and assuming no interaction between channels

$$|V_{out}|/|V_{in}| = R_a/R_b$$

If a simple tuned circuit bandpass filter is used, in order to cross over evenly between channels the Q value should be $\sqrt{2^x/(2^x - 1)}$, where x is the channel spacing in octaves. In a negative feedback system this is not

critical and the value of Q can be raised to reduce the interaction, the penalty being a rise in noise at the crossover points. Error in the centre frequency of a filter has a similar effect; as a guide, approximately 1.5dB increase in noise is produced by 50% Q error, or 15x% error in centre frequency.

At a first glance it would seem desirable to make the first and last filters low and high pass respectively, but in actual fact this response is produced in a negative feedback loop using only bandpass filters. The penalty is increased noise again, but this time well outside the audio range, assuming a reasonable choice of channel frequencies has been made. Using only bandpass filters simplifies the system since only one basic filter type is required. The design of this network will now be considered.

Active bandpass filter

In some systems there could be thirty or more channels, and since there is one filter circuit per channel, this must be designed as

Performance of the five-channel tone control

- 3dB bandwidth at 1V r.m.s. signal level, controls flat: 8Hz-30kHz
- distortion at 1V r.m.s. signal level, controls flat: 100Hz-0.05%
- 1kHz-0.05%
- 10kHz-0.05%
- clipping level, controls flat: 2.9V r.m.s.

economically as possible within the limits of the specification. Assuming no inductors are to be used for the reasons mentioned before, the number of active devices should be minimized, unless component tolerances can be relaxed by using more. Close tolerance capacitors can prove especially expensive.

A simple circuit that meets these requirements is the Wien bridge derivative⁴ shown

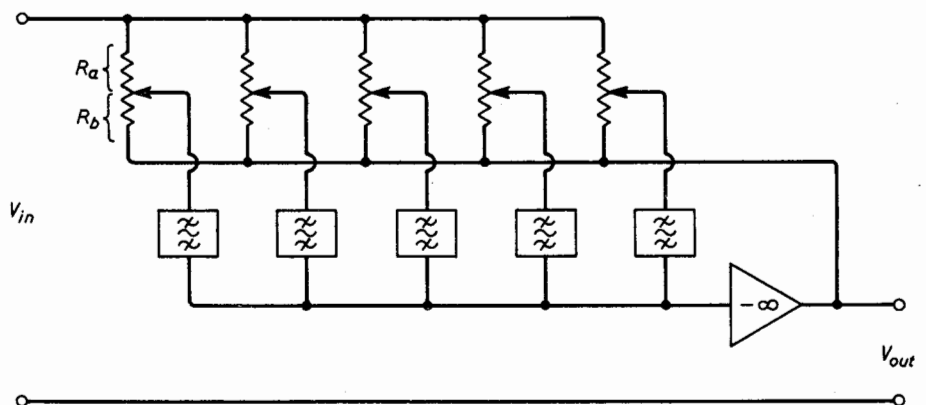


Fig. 1. Simple block diagram of the multi-channel negative feedback system.

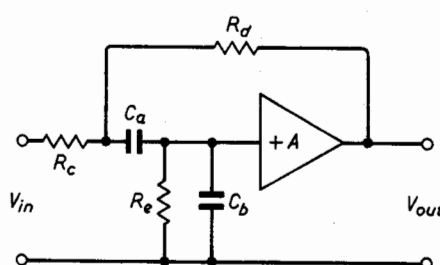


Fig. 2. Example of a band-pass active filter.

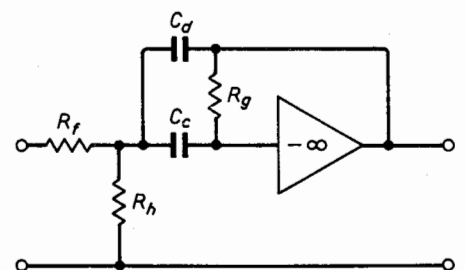


Fig. 3. Band-pass filter using multiple feedback.

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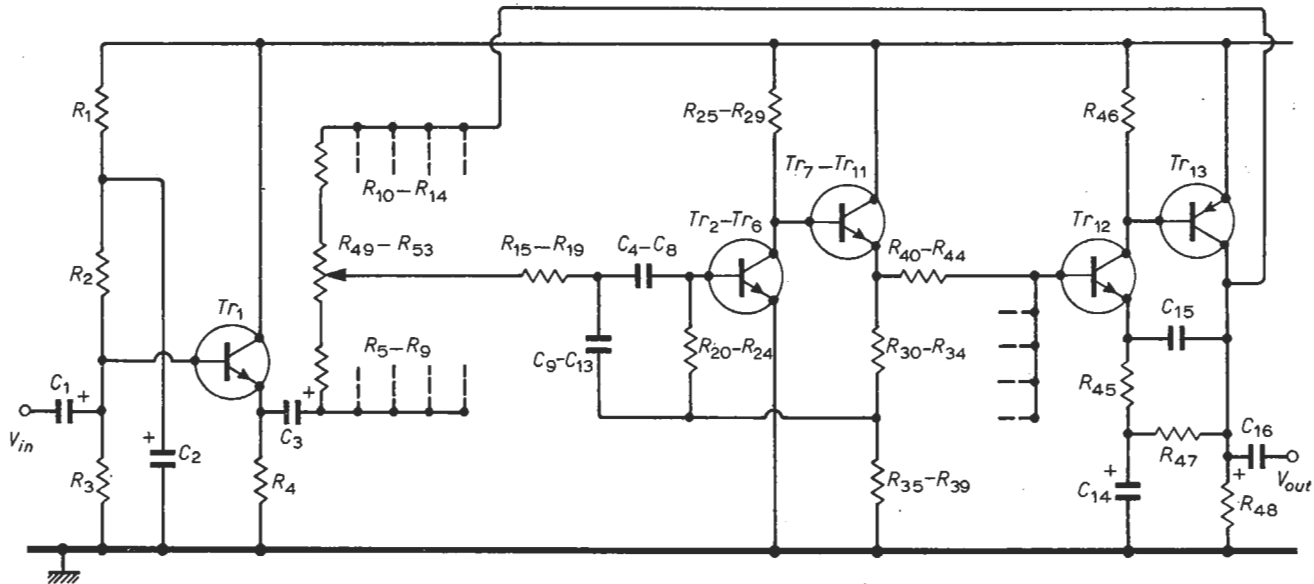


Fig. 4. Circuit of the five-channel tone control unit. Only one of the filters and linear potentiometer is shown.

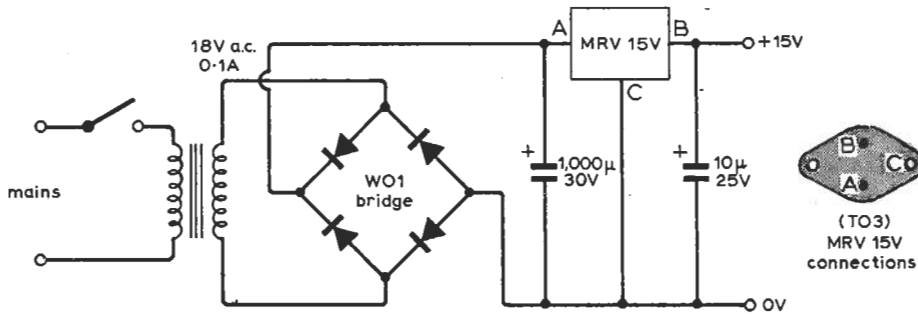


Fig. 5. Suggested power supply circuit using an integrated regulator.

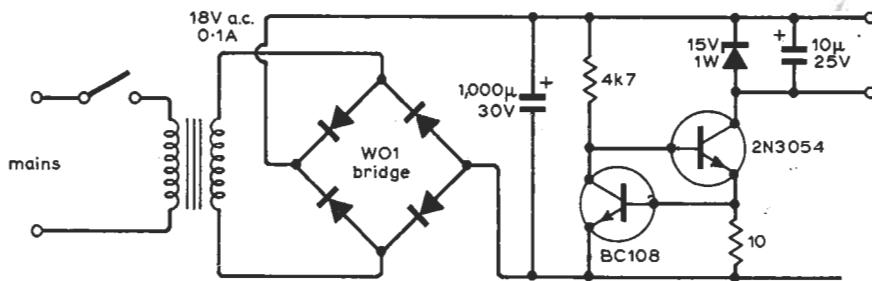


Fig. 6. Alternative discrete component power supply.

in Fig. 2. The response follows the tuned circuit law

$$V_{out}/V_{in} = -H\omega_0(j\omega)/\omega_0^2 - \omega^2 + a\omega_0(j\omega)$$

where $a = 1/Q$, ω_0 is the resonant frequency and the gain of the voltage amplifier is

$$H = 1/3(6.5 - a)$$

The component values are $C_b = C_a/2$, $R_c = 2/\omega_0 C_a$, $R_d = R_c/3$ and $R_e = 2R_c$. The most desirable feature of this circuit is that R and C values are independent of Q , and ω_0 is independent of amplifier gain H . Unfortunately, the Q value becomes extremely sensitive to the value of H for $Q \geq 1$, and the margin of stability in such cases is narrow.

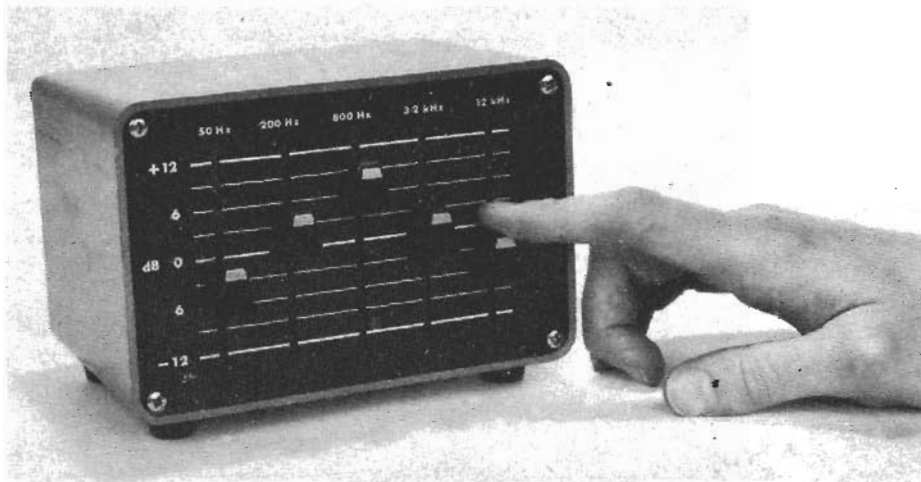
A circuit much more suited to this application⁵ consists of an inverting op-amp with multiple feedback loops (Fig. 3).

The response of this circuit is the same as before, but the component values are $C_c = C_d$, $R_f = 1/H\omega_0 C_c$, $R_h = 1/(2Q - H)\omega_0 C_c$ and $R_g = 2Q/\omega_0 C_c$. If $H = 2Q$, R_h can be left out and V_{out}/V_{in} at resonance becomes

$$V_{out}/V_{in} = -2Q^2 = R_g/2R_f.$$

The minus sign in this expression indicates a phase reversal, so the main amplifier in Fig. 1 will now need an in-phase gain to obtain an overall negative feedback relationship.

The above equations for this active filter circuit show that Q , passband gain and resonant frequency are determined solely by two identical capacitors and two resistors. The demands on the op-amp are not great, and a single bipolar transistor suffices for low Q values. The transistors are used in the circuits to follow to provide a high stage gain in addition to filtering. This reduces the noise contribution of the main amplifier, and so long as the gain is greater than the number of channels used, the dominant noise contribution is that due to the first transistor stage of the active filter. This means a signal to noise ratio of about 70dB,



Five slider potentiometer controls on the front panel can be set to represent the required amplitude frequency response.

Table 1

Channel frequency (Hz)	C_{4-13} ($\mu F \pm 10\%$)
50	0.22
200	0.056
800	0.015
3.2k	3.900p
12.8k	1.000p

which is better than most preamplifier inputs.

Practical circuit

The circuit is shown in Fig. 4. Only one filter is shown as the other four are identical, except for the values of C_x which are given in Table 1. An emitter follower Tr_1 provides a low impedance input source for the bank of control potentiometers, R_{49-53} . The fixed resistors R_{5-14} restrict the range of boost and cut to ± 12 dB. The active filter consists of a common emitter amplifier with a d.c. coupled emitter follower output. The Q value employed is unity and the passband gain at resonance should be approximately 28dB. The filter outputs are fed to the main amplifier through R_{40-44} which also provide the d.c. bias for this stage. Overall h.f. stability is obtained from the 6dB/octave roll-off provided by C_{15} and R_{45} .

The unit complete with power supply fits into a 16 x 11 x 11cm case without difficulty.

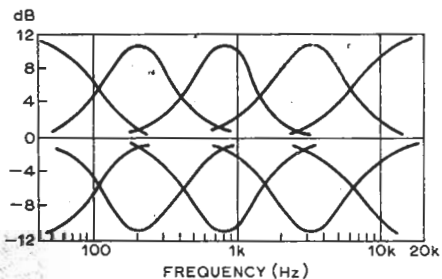
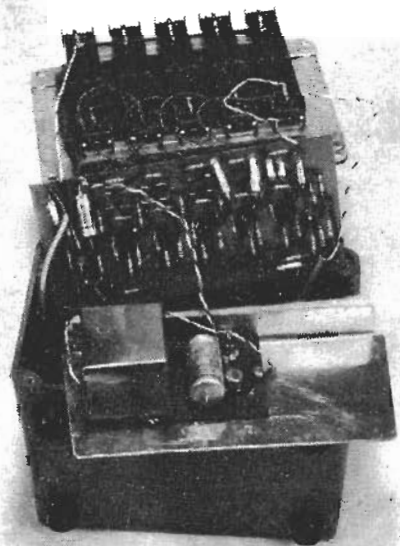


Fig. 7. Typical response curves of the five-channel unit.



Slider pots mounted on the front panel are shown at the top with the main p.c. board (centre), which carries the filter circuitry and input/output devices. The power supply is on a separate board (bottom).

Table 2

Modified filter component values for narrower channel spacing. For worst case component tolerance, channel spacing error is 30%.

Channel spacing (octaves)	Q	R_{15-19} (k Ω)	R_{20-24} (k Ω)	R_{30-34} (k Ω)	Tolerance C_{4-13}, R_{15-24} (%)
1	1.7	3.9	47	6.8	10
$\frac{1}{3}$	4.5	1.5	120	0.68	3

A suitable power supply circuit using a monolithic regulator is given in Fig. 5. An alternative discrete component version, with a "ring of two" constant current generator feeding a zener diode in parallel with the load is given in Fig. 6. Either unit offers a ripple level which is inaudible with the unit in operation.

A small point worth noting is that calibration of the potentiometers in linear dB steps does not strictly follow the mathematical law, although only 10% error is produced over a 12dB range.

More channels

The performance of the five channel unit is encouraging enough to consider expanding the controls in range and number. As for range of control, about ± 25 dB is the most that would normally be required, even for special effects. One can obtain this range by reducing the values of R_{5-14} down to 2.7k Ω . To make sure that the overload margin is maintained under all conditions, it may be necessary to increase the standing current in Tr_1 and Tr_{13} to provide sufficient drive voltage for the potentiometer bank. Transistors Tr_1 and Tr_{13} may then have to be types of a higher dissipation rating. The number and spacing of controls will depend chiefly on application, thirty controls of one third octave spacing being a reasonable limit. The filter circuits can remain the same as the five channel unit; modified resistor values for two higher values of Q are given in Table 2. Using these modified circuits does not significantly alter the capacitor values for a given frequency, which are given by the equation

$$C(\mu F) = 1/(\omega_0 \sqrt{R_f \cdot R_g}) \approx 11.8/f_0(\text{Hz})$$

Components

Values for the power supply components are shown in Fig. 5 or Fig. 6.

Transistors
 Tr_{13} - BC212 All others BC109

Capacitors
 C_1 - 1 μ /10V C_{14} - 50 μ /10V
 C_2 - 10 μ /15V C_{15} - 0.005 μ
 C_3 - 10 μ /15V C_{16} - 10 μ /15V
 C_{4-8} } - C_x (see table 1)
 C_{9-13} }

Resistors

R_1 - 47k R_{30-34} - 10k
 R_2 - 47k R_{35-39} - 680
 R_3 - 100k R_{40-44} - 22k
 R_4 - 1k R_{45} - 100
 R_{5-9} } - 3.3k R_{46} - 10k
 R_{10-14} } - 3.3k R_{47} - 4.7k
 R_{15-19} - 6.8k R_{48} - 1k
 R_{20-24} - 27k * R_{49-53} - 10k lin
 R_{25-29} - 100k

*Slider pots are "Alp" type LV60 (mono) or LG60 (stereo). The cheaper Radiohm types are also suitable.

REFERENCES

1. Baxandall, P. J., "Negative Feedback Tone Control", *Wireless World*, Oct. 1952.
2. Ambler, R., "Tone-balance Control", *Wireless World*, March 1970.
3. Hutchinson, P. B., "Tone Control Circuit", *Wireless World*, Nov. 1970.
4. Sallen and Key, *Transactions I.R.E.*, CT-2 No. 1, March 1970.
5. Huelsman, L. P., "Theory and Design of Active RC Circuits", McGraw-Hill, 1968.

Conferences and Exhibitions

- 1973 European Microwave Conference**
 Sept. 4-7 Brussels (Dr. G. Hoffman, Secretary General, ST Pietersnieuwstraat 41, B-9000 Ghent, Belgium)
LASER 73
 Sept. 4-7 Munich (Munchener Messe- und Ausstellungsgesellschaft, Theresienhohe 13, Munich, Germany)
Royal Television Society Convention
 Sept. 6-9 Cambridge (Royal Television Society, 166 Shaftesbury Avenue, London WC2H 8JH)
Solid State Devices Conference
 Sept. 10-11 Nottingham (The Institute of Physics, 47 Belgrave Square, London SW1X 8QX)
First National Quantum Electronics Conference
 Sept. 10-13 Manchester (The Institute of Physics, 47 Belgrave Square, London SW1X 8QX)
Physics of Semimetals and Narrow-gap Semiconductors
 Sept. 12-14 Cardiff (Dr. J. Aubrey, Dept. of Applied Physics, UWIST, King Edward VII Avenue, Cardiff CF1 3NU)
First Indian Electronics Trade Fair
 Sept. 15-17 Bombay (Taj Mahal Inter-Continental Hotel, Division of Trade Fairs and Exhibitions, Apollo Bunder, Bombay 1, India)
Switching and Signalling in Telecommunications
 Sept. 16-22 Birmingham (I.E.E. Savoy Place, London WC2R OBL)
IEEE Electronics and Aerospace Systems Conference
 Sept. 17-19 Washington (I.E.E.E., 345 East 47th Street, New York, N.Y. 10017, U.S.A.)
Eleventh Modulator Symposium
 Sept. 18-19 New York (I.E.E.E., 345 East 47th Street, New York, N.Y. 10017, U.S.A.)
Electronic Prosthetics Conference
 Sept. 19-21 Lexington (College of Engineering, University of Kentucky, Lexington, Kentucky 40506)

FOR TRIMMABLE
FREQUENCY

1 - Multiply
C4-8 & C4-13
by 1.2
(approx.)

- Add Rb.
in Fig 3.

- 15k Pot for
a 5 CH unit
(NOT NECESSARY THOUGH)

10k Pot for a
10. or 30 ch.
unit
or a 6.8k trim
pot and a
- 2 to 3k resistor